Presentation for Assistant Professor position

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Curriculum Vitae



Education

Nov. 2012 - Dec. 2015 Ph.D in Computer Science LIFAT, Poly-Tech Tours Tours. France

2007 - 2009

Master of Tech. in Mecatronics & Robotics Indian Institute of Engineering Science and Technology (IIEST) Shibpur, West Bengal, India

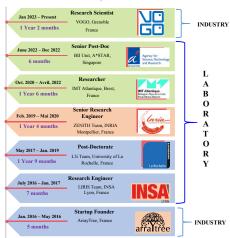
2003 - 2007

Bachelor of Tech. in Information Tech. West Bengal University of Technology West Bengal, India

Professional Experiences



After Ph.D | 7 Years



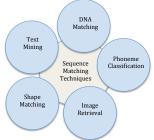
Summary of Presentation

- Ph.D Work : Comparative Study of *Dynamic Time Warping (DTW)*
- Ph.D Work: Flexible Sequence Matching
- Ph.D Work : Exemplary Sequence Cardinality
- What is Matrix Profile
- Post-Doc Work : AAMP algorithm
- Post-Doc Work : kNN Matrix Profile



Time Series Matching to "Word Spotting"

- Modern digital devices accumulated huge time series data
- Important need to : querying and indexing
- Prevalent ares are:



- Many techniques extracts significant "features"
- One is image column based



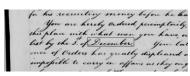


Fig: Sample scanned image

llexandria

Fig: Sample key-word Alexandria

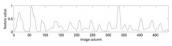


Fig: Normalized projection profile



Fig: Normalized upper word profile 1

¹T.M.Rath and R.Manmatha,"Word spotting for historical documents", IJDAR,vol.9,no.2-4,pp.139-152,Aug.2006.

Architecture de «Word Spotting»

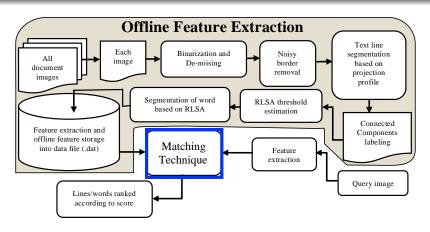


Fig: The block diagram of word spotting system

Feature Extraction

Column Based Feature Extraction:

| N° | Feature set Description |
|-----|---|
| F1. | Projection Profile |
| F2. | Background-to-ink transition |
| F3. | Upper Profile |
| F4. | Lower Profile |
| F5. | Distance between upper and lower Profile |
| F6. | Number of foreground pixels |
| F7. | Center of gravity (C.G.) of foreground pixels |
| F8. | Transition at C.G. |

Features Based on «Slit Style HOG»

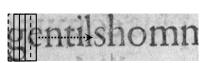


Fig: Feature extraction using slit style sliding window



Fig: Block normalization technique

Datasets

| Dataset Name | No of Query Images | No of Target Words | No of Pages | Properties |
|------------------------|--------------------------|--------------------------|----------------|---|
| GW-15-Col GW-90-Col | 15 90 | 2340 4860 | 10 20 | Hand Written manuscript of George Washington(GW) (1755) |
| GW-15-HOG | 15 | 675 (lines) | 20 | (1755) |

Setters Virginia Sergeant Recruit, October Regiment-Captain Instructions bumbalant Decomba Winchester Company

Fig: Some query images used for GW dataset

to it delaying the execution of the tell year Momens what he much is the proceedings of the term of the set of

Fig: The sample page from GW dataset

given, the Grand to day beginn Balyis excluded to lack agree home the command of the lack agree home the command of the Marian to the the same the lack and the same the lack and the same the lack and lack and the lack and the

Fig: Some segmented text lines from GW dataset

Datasets

| Dataset Name | No. of Query Images | No. Target Words | No of Pages | Properties |
|--------------|---------------------------|---------------------|----------------|-----------------|
| Japan-4-HOG | 4 | 1575 | 92 | Japanese Script |

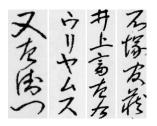


Fig: Some query images used for Japanese dataset



Fig: Sample page from the Japanese dataset

Comparative Study of Sequence Matching Techniques for "Word Spotting"

"Dynamic Time Warping"

- DTW measures similarity between two time series $X = x_1, x_2, x_3, ..., x_p$ and $Y = y_1, y_2, y_3, ..., y_a$
- We construct a $p \times q$ matrix where the (i^{th}, j^{th}) element of the matrix contains the distance: $\mathfrak{D}(x_i, y_i) = (x_i - y_i)^2$
- The path cost matrix \mathfrak{V} is calculated by using \mathfrak{D}
- The best warping path (W) is contiguous set of matrix elements, which defines an optimal mapping between X and Y.



Fig: The distance matrix



Fig: The "path cost" matrix



Fig: The "warping path" algorithm

$$\mathfrak{P}_{(1,1)} = \mathfrak{D}_{(1,1)}$$

$$\mathfrak{P}_{(i,0)} = \mathfrak{P}_{(i-1,0)} + \mathfrak{D}_{(i,0)}$$

$$\mathfrak{P}(i,0) = \mathfrak{P}(i-1,0) + \mathfrak{D}(i,0)$$

$$1 < i \le p$$

$$\mathfrak{P}_{(0,j)} = \mathfrak{P}_{(0,j-1)} + \mathfrak{D}_{(0,j)}$$

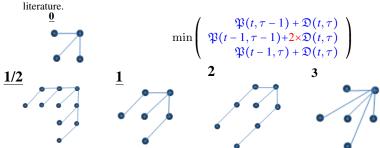
$$1 < j \le q$$

$$\mathfrak{P}_{(i,j)} = \mathfrak{D}_{(i,j)} + min \begin{cases} \mathfrak{P}_{(i,j-1)} \\ \mathfrak{P}_{(i-1,j-1)} \\ \mathfrak{P}_{(i-1,j)} \end{cases}$$

$$\mathfrak{P}_{(i,j)} + \min \left\{ \mathfrak{P}_{(i-1,j-1)} \\ \mathfrak{P}_{(i-1,j)} \right\}$$

DTW with varying "step size" conditions

- In the case of classical DTW, the warping path can get stuck at some position
- To avoid such situation, other step size conditions of DP-path have been proposed in the literature



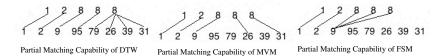
Comparative study on 6 databases

| No. | Technique | Dataset- GW-15 | Dataset- CESR-10 | Dataset- GW-HOG | Dataset- Japanese- HOG | Dataset- GW-90 | Dataset- Bentham |
|-----|-------------------------|-------------------|---------------------|--------------------|------------------------------|-------------------|---------------------|
| 1. | 0-Sym.1 | 0.3668 | 0.6449 | × | × | 0.1323 | 0.3286 |
| 2. | 0-Sym.2 (classical DTW) | 0.4576 | 0.8503 | × | × | 0.1573 | 0.4525 |
| 3. | 1-Sym | 0.3074 | 0.6922 | × | × | 0.1180 | 0.3533 |
| 4. | 1-Asym | 0.2188 | 0.220 | × | × | 0.0166 | 0.0458 |
| 5. | 2-Sym | 0.2038 | 0.5512 | × | × | 0.0513 | 0.1788 |
| 6. | 2-Asym | 0.1936 | 0.2029 | × | × | 0.0152 | 0.0417 |
| 7. | 3-Sym | 0.4324 | 0.8515 | × | × | 0.1702 | 0.4389 |
| 8. | 0.5-Sym | 0.2776 | 0.7168 | × | × | 0.1156 | 0.3901 |
| 9. | 0.5-Asym | 0.4642 | 0.8402 | × | × | 0.1663 | 0.4224 |
| 10. | SC-Band | 0.5876 | 0.7961 | × | × | × | × |
| 11. | Itakura parallelogram | 0.6017 | 0.8013 | × | × | 0.2226 | 0.5265 |
| 12. | DDTW | 0.2180 | 0.5645 | × | × | × | 0.065 |
| 13. | Value Derivative DTW | 0.2265 | 0.6510 | × | × | × | × |
| 14. | Weighted Hybrid DTW | 0.3554 | 0.8621 | × | × | 0.146 | 0.358 |
| 15. | PDTW | 0.3466 | 0.8929 | × | × | 0.157 | 0.432 |
| 16. | PDDTW | 0.2563 | 0.9564 | × | × | × | 0.178 |
| 17. | WDTW | 0.3309 | 0.5854 | × | × | × | × |
| 18. | WDDTW | 0.2431 | 0.2319 | × | × | × | × |
| 19. | LDTW | 0.5374 | 0.7577 | × | × | 0.229 | 0.499 |
| 20. | Sin transform | 0.4213 | 0.6790 | × | × | 0.102 | 0.335 |
| 21. | Cos transform | 0.2426 | 0.5653 | × | × | × | × |
| 22. | Hilbert transform | 0.5380 | 0.8907 | × | × | 0.245 | 0.566 |
| 23. | SSDTW | 0.3349 | 0.8409 | 0.645 | 0.7295 | 0.1181 | 0.3276 |
| 24. | DTW-CW | 0.3603 | 0.8756 | 0.643 | 0.734 | 0.1358 | 0.3537 |
| 25. | MJ-DTW | 0.3413 | 0.7779 | × | × | 0.1835 | 0.4370 |
| 26. | LCSS | 0.0354 | 0.1496 | × | × | × | × |
| 27. | 1DLCSS | 0.0489 | 0.2006 | × | × | × | × |
| 28. | DDLCSS | 0.0489 | 0.2024 | × | × | × | |
| 29. | OSB | 0.2785 | 0.7982 | 0.3914 | 0.6089 | × | × |
| 30. | MVM | 0.2026 | 0.5168 | 0.3495 | 0.3970 | × | × |
| 31. | CDP | 0.3619 | 0.9176 | 0.7194 | 0.7473 | 0.1713 | 0.4354 |
| 32. | Fast-DTW | 0.4348 | 0.7806 | × | × | × | × |

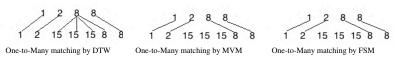
- Tanmoy Mondal, Nicolas Ragot, Jean-Yves Ramel, Umapada Pal, "Comparative Study of Conventional Time Series Matching Techniques for Word Spotting", Pattern Recognition (PR) 73:, 47-64, 2018.
- Tanmoy Mondal, Nicolas Ragot, Jean-Yves Ramel, Umapada Pal, Performance evaluation of DTW and its variants for word spotting in degraded documents, ICDAR 2015: 1141-1145

Flexible Sequence Matching

Flexible Sequence Matching



- DTW cannot ignore noisy elements
- MVM cannot have many-to-one and one-to-many matching. It is forced to find the same number of correspondences
- The FSM algorithm has overcome these two problems



- DTW cannot give correct match
- MVM and FSM are able to give the right matches by skipping noisy elements

Formation de l'algorithme FSM

- FSM creates a relation \mathbb{R} between x (query) and y (target), of lengths p and q: $x = (x_1, x_2,, x_p)$ and $y = (y_1, y_2,, y_q); p \le q$
- It finds $y'(y' \subset y)$ such that x best matches with y'.
- The difference matrix \mathfrak{D} : $\mathfrak{D}_{i,j} = \sqrt{(y_j x_i)^2}$; $1 \le i \le p$; $1 \le j \le q$

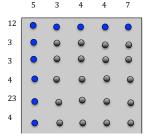


Fig: La matrice de distance

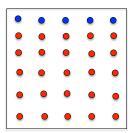


Fig: La DAG (G) ou matrice «path cost» \$\mathfrak{P}\$

$$\mathfrak{P}(1,j) = \mathfrak{D}_{1,j} \text{ if } 1 \le j \le q$$

Formation de l'algorithme FSM ..

Chaque cellule appartenant au ith ligne est calculée en choisissant le nœuds parents à: – Ligne précédente (i – 1)
 – Aux colonnes (k) à partir de ((i – 1) – elasticity) Ã ((i – 1) + elasticity)

$$max[1, (i-1) - elasticity] \le k \le min[q, (i-1) + elasticity]$$

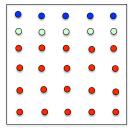


Fig: La matrice de «path cost»

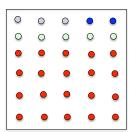


Fig: La matrice de «path cost»

Formation de l'algorithme FSM ..

- Par rapport à chacun de ces nœuds parents, les nœuds enfants ne peuvent appartenir qu' à :
 - Ligne Suivante
 - Colonne suivante (k+1) jusqu'à (k+1) + elasticity $|k-(i-1)|^{th}$

$$2 \le i \le p$$

$$k+1 \le j \le min(q, (k+1) + elasticity - max(0, \{k-(i-1)\}))$$

$$\{\mathfrak{P}(i-1, k) + \mathfrak{D}_{i,j} + (\mathfrak{S} \times (j-(k+1)))\}$$

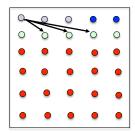


Fig: La matrice de «path cost»

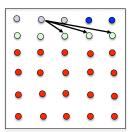


Fig: La matrice de «path cost»

Formation of the FSM algorithm ..

- Other possible links are:
 - «many-to-one» : link just below (i-1,j) à (i,j) : $\{\mathfrak{P}(i-1,j) + \mathfrak{C} + \mathfrak{D}_{i,j}\}$ «one-to-many» : link just at left (i,j-1) à (i,j) : $\{\mathfrak{P}(i,j-1) + \mathfrak{C} + \mathfrak{D}_{i,j}\}$
- A small penalty ($\mathfrak{C} = mean(\mathfrak{M}_b^{merged})$) is introduced to limit the numbers of many-to-one and one-to-many matching

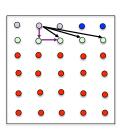


Fig: The path cost matrix

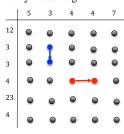


Fig: The illustration of one-to-many (blue) and many-to-one (red) matching on toy examples

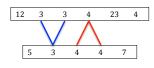


Fig: Corresponding matching elements of the query and target vectors

Some Visual Results

- FSM has outperformed other sequence matching techniques
- The noise or outliers (derivatives also) skipping capability helps FSM
- The special characteristics of FSM is helpful in other domains e.g. finance, video retrieval, shape matching etc.

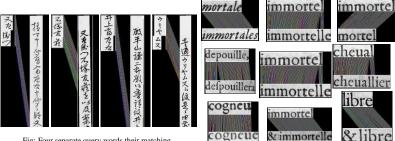


Fig: Four separate query words their matching

Fig: Example of matching by FSM

- Tanmoy Mondal, Nicolas Ragot, Jean-Yves Ramel, Umapada Pal, "Flexible Sequence Matching Technique: An Effective Learning-Free Approach for word-spotting", Pattern Recognition 60: 596-612 (2016)
- Tanmov Mondal, Nicolas Ragot, Jean-Yves Ramel, Umapada Pal, Flexible Sequence Matching Technique: Application to Word Spotting in Degraded Documents, ICFHR 2014: 210-215, 2013

Exemplary Sequence Cardinality

Introduction

- ESC has all the qualities as FSM
- ESC can skip noisy elements from query
- Choosing query become more easier
- The proposed system, is more robust to:
 - Degradation noise
 - Word derivatives
 - Improper segmentation issues
- For example, in French, the word *cheval* (*horse*) can have derivatives like "*chevallier*", "*chevalerie*", "*chevalier*".

ESC: Mathematical Formulation

- To make the 1st element of the query skip-able, one null element (0) is is added at the beginning of both the query and target sequence (contrary to FSM)
- Modified dissimilarity matrix (Q) is created
- Another matrix $(\mathcal{M}_{i,j})$ is utilized to follow the indexes
- The immediate child of a skip-able node are connected with parents of their immediate parents (Grand parents).

$$\mathfrak{Q}_{\mathbf{i},\mathbf{j}} = \left\{ \begin{array}{ll} \widehat{\mathfrak{D}}_{1,j} & 1 \leq j \leq q+1 \\ skipCost & \text{if } skipCost < \widehat{\mathfrak{D}}_{i,j} \\ \widehat{\mathfrak{D}}_{i,j} & \text{Sinon} \end{array} \right.$$

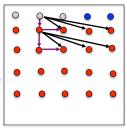


Fig: The "path cost" matrix

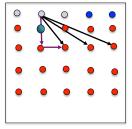


Fig: The "path cost" matrix

ESC: Formulation Mathématique

• Le chemin le plus court entre chaque paire de nœuds accessibles dans \mathbb{G} peut être trouvé à partir de la matrice «path cost» $\mathcal{P}_{i,j}$.

$$\begin{split} \mathcal{P}_{1,j} &= \mathfrak{Q}_{1,j} &\quad \text{if } 1 \leq j \leq q+1 \\ \left\{ \begin{aligned} \mathcal{P}_{i-1,k} &+ \mathfrak{Q}_{i,j} + \\ \left(skipCost \times \left(j - \left(k + 1 \right) \right) \right) \right\} \\ \left\{ \begin{aligned} \mathcal{P}_{i,j-1} &+ \mathfrak{C} + \mathfrak{Q}_{i,j} \right\} \\ \left\{ \begin{aligned} \mathcal{P}_{i-1,j} &+ \mathfrak{C} + \mathfrak{Q}_{i,j} \right\} \end{aligned} \end{aligned} \right) &\quad \text{if } \mathfrak{L} \end{split}$$

$$\mathfrak{L}: \left\{ \begin{array}{l} \{2 \leq i \leq q+1\} \\ \{(i-1)-elasticity \leq k \leq (i-1)+elasticity\} \\ \{k+1 \leq j \leq (k+1)+elasticity-|k-(i-1)|\} \end{array} \right\}$$

ESC: Mathematical Formulation

- The back tracking process would start from the cell at the last row and at the j^{th} column of the path cost matrix \mathcal{P} , where $p + 1 \le j \le q + 1$
- ESC has the same complexity as FSM i.e. $\Theta((2.|q-p|^2).p)$

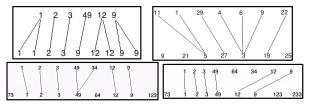


Fig: Matching ability of ESC on toy examples



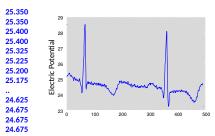
Fig: Matching ability of ESC on some artificial images

Similarity Search in Time Series

What are Time Series? 1 of 2

A time series is a collection of observations made sequentially in time.

More than most types of data, time series lend themselves to visual inspection and intuitions...



For example, looking at the numbers in this blue vector tells us nothing.

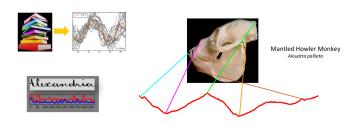
But after *plotting* the data, we can recognize a heartbeat, and possibly even diagnose this person's disease.

^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

What are Time Series? 2 of 2

As an aside... (not the main point for today)

Many types of data that are not *true* time series can be fruitfully transformed into time series, including DNA, speech, textures, core samples, ASCII text, historical handwriting, novels and even *shapes*.



^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

- A similarity measure compares two time series and produces a number representing their similarity
 - A distance measure is the opposite of similarity measure
- Lockstep Measures
 - Euclidean Distance
 - Correlation Coefficient
 - Cosine Similarity
- Elastic Measures
 - Dynamic Time Warping
 - · Edit Distance
 - · Longest Common Sub-sequence

^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

Euclidean Distance Metric

Given two time series

$$x = x_1...x_n$$

and

$$\mathbf{y} = \mathbf{y}_1 ... \mathbf{y}_n$$

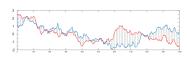
their z-Normalized Euclidean distance is defined as:

$$\widehat{x}_i = \frac{x_i - \mu_x}{\sigma_x} \qquad \widehat{y}_i = \frac{y_i - \mu_y}{\sigma_y}$$

$$d(x,y) = \sqrt{\sum_{i=1}^{n} (\widehat{x_i} - \widehat{y_i})^2}$$

function d = EuclideanDistance(x,y)
d = sqrt(sum((x-y).^2));





^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

Pearson's Correlation Coefficient

- Given two time series x and y of length m.
- Correlation Coefficient:

$$corr(\mathbf{x}, \mathbf{y}) = \frac{(E(\mathbf{x}) - \mu_x)(E(\mathbf{y}) - \mu_y)}{\sigma_x \sigma_y} = \frac{\sum_{i=1}^m x_i y_i - m \mu_x \mu_y}{m \sigma_x \sigma_y}$$

• Where
$$\mu_x = \frac{\sum_{i=1}^{m} x_i}{m}$$
 and $\sigma_x^2 = \frac{\sum_{i=1}^{m} x_i^2}{m} - \mu_x^2$

· Sufficient Statistics:

$$\sum_{i=1}^{m} x_i y_i \quad \sum_{i=1}^{m} x_i \quad \sum_{i=1}^{m} y_i \quad \sum_{i=1}^{m} x_i^2 \quad \sum_{i=1}^{m} y_i^2$$

The sufficient statistics can be calculated in one linear scan. Given the sufficient statistics, correlation coefficient is a constant operation. Note the use of the dot product, which is the key component of many lockstep measures.

^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

Relationship with Euclidean Distance



$$d(\widehat{\mathbf{x}}, \widehat{\mathbf{y}}) = \sqrt{2m(1 - corr(\mathbf{x}, \mathbf{y}))}$$

- Maximizing correlation coefficient can be achieved by minimizing normalized **Fuclidean distance and vice versa**
- Correlation coefficient is bounded between -1 and 1, while z-normalized Euclidean distance is bounded between zero and a positive number dependent on m



m = Length of Sub-Sequence

^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix Profile Tutorial Part2.pdf

Working Formula



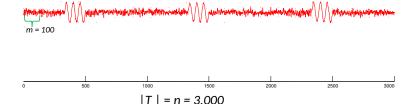
$$d(\widehat{\boldsymbol{x}},\widehat{\boldsymbol{y}}) = \sqrt{2m(1 - \frac{\sum_{i=1}^{m} x_i y_i - m\mu_x \mu_y}{m\sigma_x \sigma_y})}$$

 We will use the above z-Normalized Euclidean distance as the similarity measure for the rest of the presentation

^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

What is Matrix Profile?

- Intuition behind the Matrix Profile: Assume we have a time series T, lets start with a synthetic one...



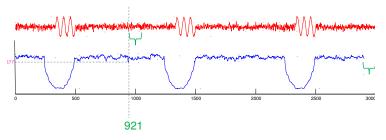
^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

What is Matrix Profile?

We can create a companion "time series", called a Matrix Profile or MP.

The matrix profile of a time series T, records at the *i*th location the distance of its nearest neighbor sub-sequence under z-normalized Euclidean Distance

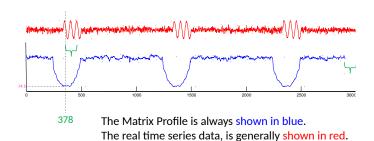
For example, in the below, the sub-sequence starting at 921 happens to have a distance of 177.0 to its nearest neighbor (wherever it is).



^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

What is Matrix Profile?

Another example. In the below, the sub-sequence starting at 378 happens to have a distance of 34.2 to its nearest neighbor (wherever it is).

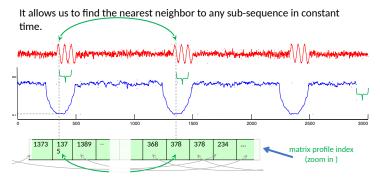


^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

What is Matrix Profile?

We can create another companion sequence, called a matrix profile index (MPI).

The MPI contains integers that are used as pointers



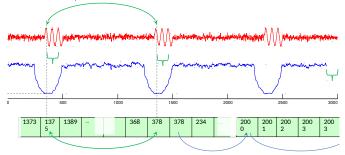
^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

What is Matrix Profile?

Note that the pointers in the matrix profile index are not necessarily symmetric.

If A points to B, then B may or may not point to A

An interesting exception, the two smallest values in the MP must have the same value, and their pointers must be mutual. This is the classic *time series motif*.

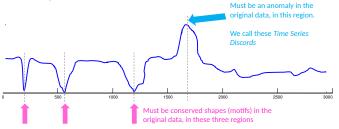


^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

How to "read" a Matrix Profile?

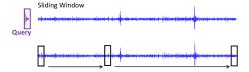
Where you see relatively low values, you know that the sub-sequence in the original time series must have (at least one) relatively similar sub-sequence elsewhere in the data (such regions are "motifs" or reoccurring patterns)

Where you see relatively high values, you know that the sub-sequence in the original time series must be unique in its shape (such areas are "discords" or anomalies).



^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

Distance Profile



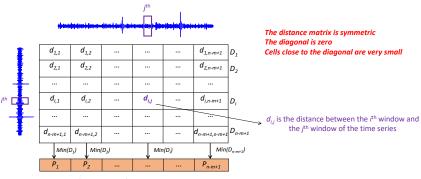
Compute the z-normalized Euclidean distance between Query and each window (subsequence) in the time series. We would obtain a vector like this:



Recall, n is the length of the blue time series and m is the length of the query

^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix Profile Tutorial Part2.pdf

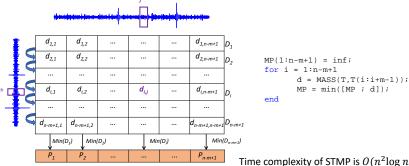
Matrix Profile from Distance Profiles



Matrix Profile: a vector of distance between each subsequence and its nearest neighbor

^{*} Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf

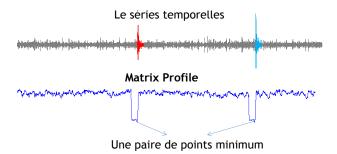
STMP: Scalable Time Series Matrix Profile Algorithm



Matrix Profile: a vector of distance between each subsequence and its nearest neighbor

Time complexity of STMP is $O(n^2 \log n)$ Space complexity of STMP is O(n)

^{*}Slide credit: Eamonn Keogh; https://www.cs.ucr.edu/~eamonn/Matrix_Profile_Tutorial_Part2.pdf



Le "Matrix Profil" a deux points minimum. Cette paire de points minimum correspond au 1^{er} motif de la série temporelle. (la paire de sous-séquences la plus proche de la série temporelles)

Produit scalaire de la *ième* fenêtre et de la *jème* fenêtre. Une fois que nous connaissons $QT_{i,j}$, il faut du temps à O(1) pour calculer $d_{i,j}$

$$d_{i,j} = \sqrt{2m\left(1 - \frac{QT_{i,j} - m\mu_i\mu_j}{m\sigma_i\sigma_j}\right)}$$

Nous avons précalculé et stocké les Moyennes et les STDs dans l'espace O(n)

La relation entre $QT_{i,j}$ et $QT_{i+1,j+1}$

$$QT_{i+1,j+1} = QT_{i,j} - t_it_j + t_{i+m}t_{j+m}$$
 O(1) time complexity!

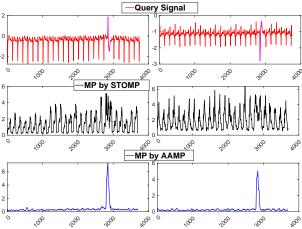


Fig: Top: different time series of the ECG dataset; Middle: matrix profile generated by normalized Euclidean z distance, using STOMP; Bottom: Matrix profile generated by non-normalized Euclidean distance, using AAMP

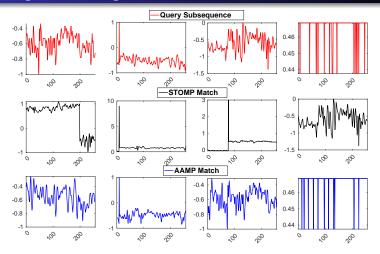


Fig : Top: Four subsequences of length 50 from the sheep database; Middle: nearest neighbors obtained by STOMP; Bottom: Nearest neighbors obtained by AAMP



Fig : Exemple d'exécution AAMP sur une série temporelle de longueur n = 10, et avec longueur de sous-séquence m = 4

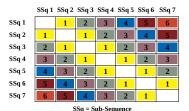


Fig: Les sous-séquences sont organisées sous forme de matrice pour mieux comprendre l'algorithme AAMP

 $D_{i,j}$: Euclidean distance between $T_{i,m}$ and $T_{j,m}$ $D_{i-1,j-1}$: Euclidean distance between $T_{i-1,m}$ and $T_{j-1,m}$

$$D_{i,j} = \sqrt{D_{i-1,j-1}^2 - \left(t_{i-1} - t_{j-1}\right)^2 + \left(t_{i+m-1} - t_{j+m-1}\right)^2}$$

 Reza Akbarinia, Bertrand Cloez, Tanmoy Mondal, Florent Masseglia; Efficient Matrix Profile Algorithms for Normalized and Non-Normalized Distances: soumis en KDD: 2021;

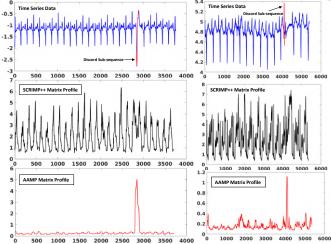


Fig : Top: two time series from a real ECG database. Discordances visible in these time series are marked by the color red. Middle: the matrix profile, obtained by the SCRIMP++ algorithm; Bottom: the profile of the matrix, obtained by the AAMP algorithm.

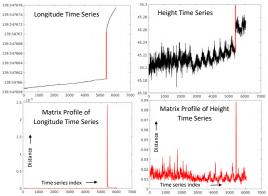


Fig: **Top:** the longitude and height time series of Seismic dataset (outliers are marked by red color); **Bottom:** the matrix profile obtained by AAMP algorithm.

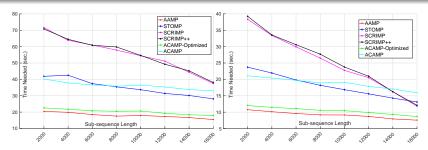


Fig: The execution times of six algorithms with increasing the subsequence length (m): a) Execution time of the six algorithms on a time series of length 68000 (protein dataset). b) Execution time of the six algorithms on a time series of length 50000 (sheep dataset).

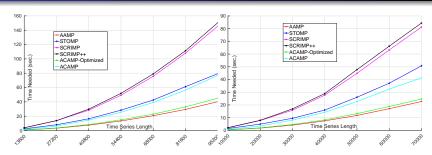
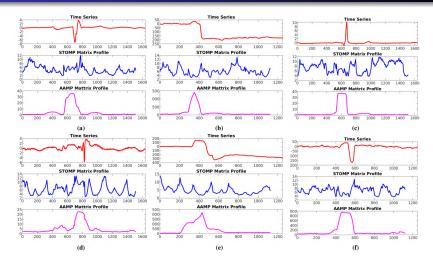
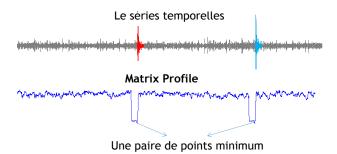


Fig : The execution time of six algorithms are plotted with the increase of time series length (n): c) Execution time of the six algorithms on variable time series length (protein dataset) with m = 256. d) execution time of the six algorithms on variable time series length (sheep dataset) with m = 256.



kNN Matrix Profile

Recap: What is 1NN Matrix Profile



Le "Matrix Profil" a deux points minimum. Cette paire de points minimum correspond au 1er motif de la série temporelle. (la paire de sous-séquences la plus proche de la série temporelles)

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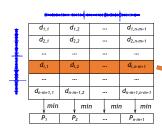
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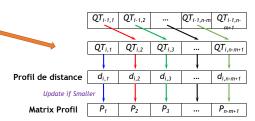
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$$QT_{i+1,j+1} = QT_{i,j} - t_it_j + t_{i+m}t_{j+m}$$
 O(1) time of

O(1) time complexity!

Recap: What is 1NN Matrix Profile

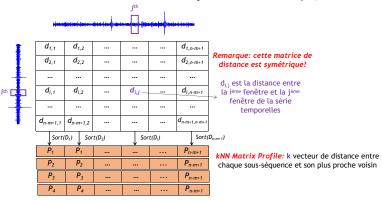




Nous pré-calculons $QT_{x,t}$ et $QT_{t,x}$ (x=1,2,3,...,n-m+1). Puis itérer à travers i=2, 2, 3, ..., n-m+1

kNN Matrix Profile

- Technique proposed for the formulation of kNN Matrix Profile
- Obtain distance with query sub-sequences and the target-1 then the target-2 until the Kth target
- Continue to update the $(K+1)^{th}$ match; use sorting to find; the maximum value and discard it; or use the technique based on "**Priority Queue**"



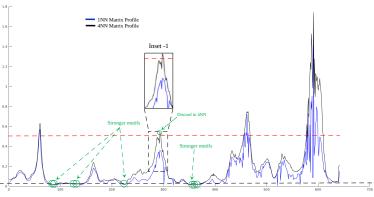


Fig. The 1NN and 4NN MP are plotted with different colors in which the motifs and discords are marked.

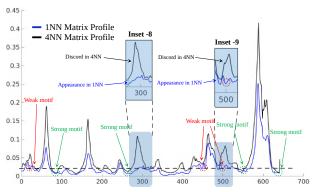


Fig: The 1NN and 4NN MP are plotted with different colors in which the motifs and discords are marked

Tanmoy Mondal, Reza Akbarinia, Florent Masseglia; "Matrix Profile Based kNN Search over Large Time Series";
 Data Mining and Knowledge Discovery (DMKD), 2023

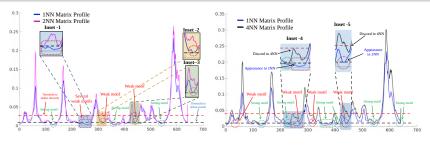


Fig. The extracted motifs and discords are illustrated in the plot : (a) The 1NN vs 2NN MP and (b) 1NN vs 4NN MP of a part of the time series is plotted

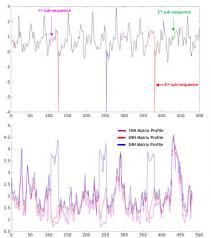


Fig. Special case of the outliers presence is depicted by considering a toy time series (top). The 1NN, 2NN and 3NN MPs are shown for the time series (bottom)

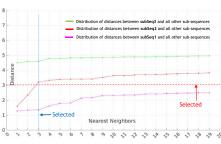


Fig. One special case of outliers detection

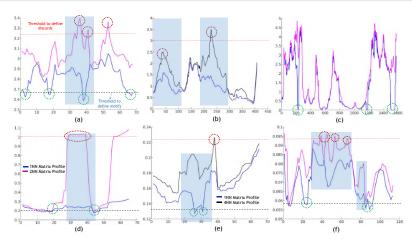
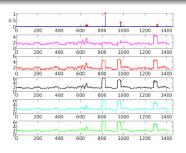


Fig. The results of UCR dataset



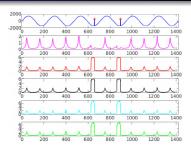


Fig. The usefulness of the kNN MP using Yahoo dataset. Time series is plotted at the top followed by $1N\ N$, $2N\ N$, $3N\ N$, $4N\ N$, and $5N\ N\ MPs$.

Table: The outlier detection accuracy of various kNN MP based on 3 high thresholds on the Yahoo dataset ("A1Benchmark-Real")

| kNN MP | Accuracies | | |
|--------|------------|-----------|-----------|
| | Threshold | Threshold | |
| | (95%) | (90%) | Threshold |
| | | | (85%) |
| 1NN | 0.317 | 0.413 | 0.469 |
| 2NN | 0.349 | 0.485 | 0.556 |
| 3NN | 0.386 | 0.509 | 0.584 |
| 4NN | 0.439 | 0.522 | 0.630 |
| 5NN | 0.458 | 0.553 | 0.653 |
| 6NN | 0.490 | 0.566 | 0.673 |
| 7NN | 0.500 | 0.610 | 0.686 |
| 8NN | 0.509 | 0.622 | 0.698 |
| 9NN | 0.522 | 0.629 | 0.704 |
| 10NN | 0.542 | 0.643 | 0.720 |

Parallel Execution of kNN Matrix Profile

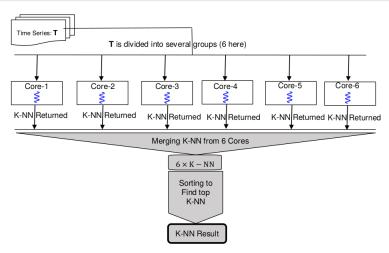


Fig: Architecture of parallel execution by using multiple cores

Performance: kNN Matrix Profile

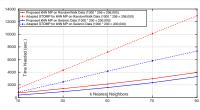
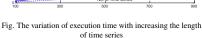
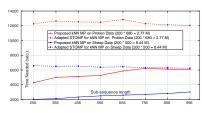


Fig. The variation of execution time with increasing k for generating kNN MP





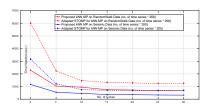


Fig. The variation of computational time with increasing the length of subsequence (m) for the protein and sheep datasets respectively

Fig. The computational time with increasing the number of cores for the random-walk and seismic datasets respectively

Thank you for your attention.. **⑤**