

# Efficient Algorithms for Knowledge Discovery from Time Series

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**Abstract**—Matrix profile is an efficient technique for knowledge extraction from time series, *e.g.*, motif and anomaly detection. Several algorithms have been yet proposed for computing it, *e.g.*, STAMP, STOMP and SCRIMP++. All these algorithms use the *z*-normalized Euclidean distance to measure the distance between subsequences. However, as we illustrate in this paper, for some datasets the non-normalized (classical) based matrix profile is more useful. Thus, efficient matrix profile techniques based on both *z*-normalized and non-normalized distances are necessary for knowledge extraction from different time series datasets.

In this paper, we propose such efficient techniques. We first propose an efficient algorithm called AAMP for computing matrix profile with the non-normalized Euclidean distance. Then, we extend our algorithm for the *p*-norm distance. We also propose two algorithms called ACAMP and ACAMP-Optimized that use the same principle as AAMP, but for calculating matrix profile by using *z*-normalized Euclidean distance. We implemented and evaluated the performance of our algorithms through experiments over real world datasets. The results illustrate that AAMP is very efficient for computing matrix profile for non-normalized Euclidean distances. They also illustrate that the ACAMP-Optimized algorithm is significantly faster than the state of the art matrix profile algorithms for the case of *z*-normalized Euclidean distance.

**Index Terms**—Time series analysis; STAMP; STOMP; All-pairs-similarity search; Motifs and discord discovery; Outliers detection; Anomaly detection; Joins



## 1 INTRODUCTION

**M**atrix profile has been recently proposed as an efficient technique to the problem of all-pairs-similarity search in time series [1]–[8]. Given a time series  $T$  and a subsequence length  $m$ , the matrix profile returns for each subsequence, the distance to the most similar subsequence in the time series. It is itself a very useful time series for data analysis, *e.g.*, detecting the motifs (represented by low values), or anomalies (represented by high values), etc.

Recently, efficient algorithms have been proposed for matrix profile computation, *e.g.*, STAMP [1], STOMP [2] and SCRIMP++ [8]. All these algorithms use the *z*-normalized Euclidean distance to measure the distance between subsequences. They are based on a technique, named as *Mueen's Algorithm for Similarity Search (MASS)* [9] for efficient calculation of *z*-normalized Euclidean distance, by exploiting the *Fast Fourier Transform (FFT)*. The *z*-normalized Euclidean distance formula used in the MASS algorithm is derived from *Pearson correlation* which works only for computing *z*-normalized Euclidean distance, and makes it inappropriate for computing classical Euclidean distance.

However, we observed that for some datasets, the non-normalized (classical) Euclidean distance is more useful for knowledge discovery. In fact, in some cases the *z*-normalization can remove rare and important information. As

an example, consider Fig. 1a (top), which shows two time series from the real ECG dataset. In Fig. 1a (middle) and (bottom), we see the matrix profiles generated for the two time series by considering *z*-normalized (using STOMP algorithm) and non-normalized Euclidean (using our AAMP) distances respectively. In this example, the matrix profiles generated using the *z*-normalized distance loose the information about the anomalies (marked by magenta color in Fig. 1a top.). But, the matrix profile calculated by using non-normalized Euclidean distance can clearly highlight those anomalies.

In addition, the *z*-normalized Euclidean distance does not necessarily provide the nearest neighbors (matches) of the subsequences from the same range of values. Hence, the match of a subsequence can come from completely different range of values and in some applications these matches could be considered as irrelevant. An example is depicted in Fig. 1b, where we show the matches for four query subsequences, taken from the time series of a real sheep dataset, representing different activities like RUNNING and WALKING (see detail of the dataset in Section 5.1.1). It is clearly visible that our proposed AAMP algorithm that uses the non-normalized Euclidean distance is capable of returning matches that are in the same range of values as the query subsequences. In Fig. 1b, we only have shown few selective examples among several others, where by using non-normalized Euclidean distance, we found better matches.

In fact, the *z*-normalized Euclidean distance based matrix profile is able to find the shape-wise matches from any range of values and that's why the shape-wise similarity could be found irrespective of the numerical values. This is an advantage for

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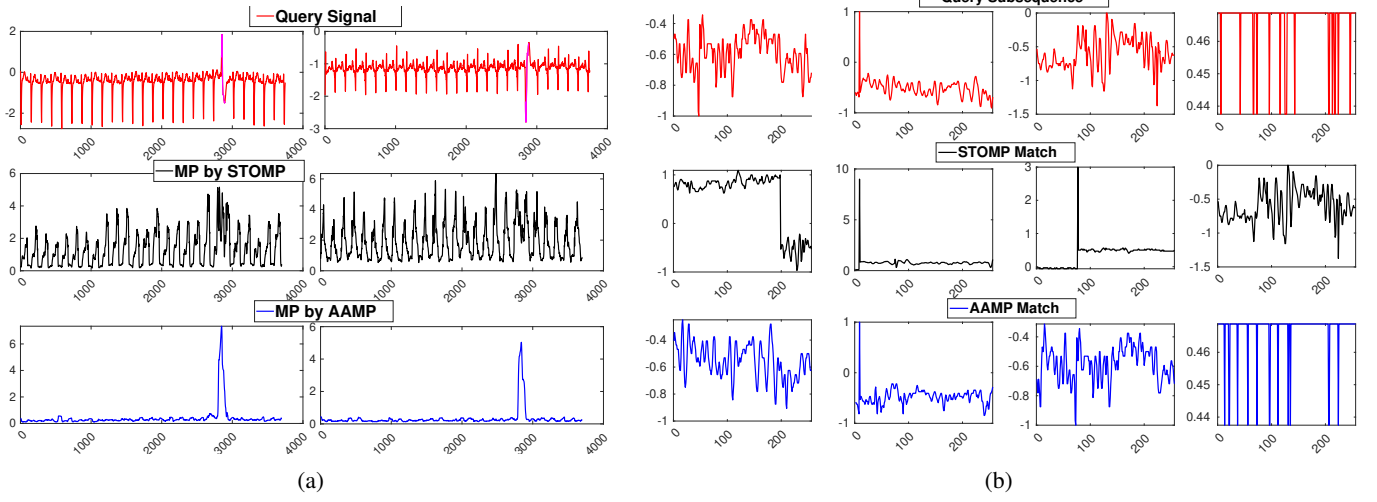


Figure 1: a) **Top:** example of two different time series from ECG dataset; **Middle:** matrix profile generated by  $z$ -normalized Euclidean distance using STOMP algorithm; **Bottom:** matrix profile generated by non-normalized Euclidean distance using our AAMP algorithm. b) **Top:** four subsequences of length 50 from sheep dataset; **Middle:** the nearest neighbors obtained by STOMP; **Bottom:** the nearest neighbors obtained by AAMP are in the same range as the queries, while the results obtained by STOMP are in very different ranges.

some applications, but a disadvantage for others (*i.e.*, those that need the matches from the same range). This is why, a combination of both  $z$ -normalized and non-normalized based matrix profiles is necessary for knowledge extraction in a wide range of applications.

In this paper, we provide efficient techniques for the calculation of matrix profile for both  $z$ -normalized and non-normalized distances. Our contributions are as following:

- We propose an efficient algorithm called AAMP for computing matrix profile with the non-normalized Euclidean distance. AAMP is executed in a set of iterations, such that in each iteration the distance of subsequences is incrementally computed. We also extend AAMP to compute matrix profile for the  $p$ -norm distance that is more general than the Euclidean distance which is actually a 2-norm distance.
- We propose an algorithm called ACAMP that uses the same principle as AAMP but for the  $z$ -normalized Euclidean distance. In ACAMP, we use an incremental formula for computing the  $z$ -normalized distance that is based on some variables, calculated incrementally in a sliding window that moves over the subsequences of the time series. We also propose an improved version of the ACAMP algorithm, called ACAMP-optimized, that is significantly faster than ACAMP.
- We implemented our algorithms and compared them with the state of the art algorithms on matrix profile, *i.e.*, STOMP, SCRIMP and SCRIMP++, using several real world datasets. The results show excellent performance gains. They show that AAMP and ACAMP-optimized are significantly faster than the state-of-the-art algorithms for matrix profile computation. They also illustrate the utility of detecting discords/outliers in datasets by using AAMP based on the non-normalized Euclidean distance

over STOMP, SCRIMP and SCRIMP++ that are based on the  $z$ -normalized Euclidean distance.

It is worth mentioning that our algorithms, *i.e.*, AAMP and ACAMP, are exact, anytime and incrementally maintainable. They take a deterministic execution time that only depends on the time series and subsequence length.

The rest of this paper is organized as follows. In Section 2, we give the problem definition. In Section 3, we describe our AAMP algorithm for computing matrix profile with non-normalized Euclidean and  $p$ -norm distances. In Section 4, we propose the ACAMP algorithm for  $z$ -normalized distance. Section 5 presents the experimental results. Section 6 discusses related work and Section 7 concludes the article.

## 2 PROBLEM DEFINITION

In this section, we give the formal definition of the matrix profile, and describe the problem which we address in this article.

**Definition 2.1.** A time series  $T$  is a sequence of real-valued numbers  $T = \langle t_1, \dots, t_n \rangle$  where  $n$  is the length of  $T$ .

A subsequence of a time series is defined as follows.

**Definition 2.2.** Let  $m$  be a given integer value such that  $1 \leq m \leq n$ . A subsequence  $T_{i,m}$  of a time series  $T$  is a continuous sequence of values in  $T$  of length  $m$ , starting from position  $i$ . Formally,  $T_{i,m} = \langle t_i, \dots, t_{i+m-1} \rangle$  where  $1 \leq i \leq n - m + 1$ . We denote  $i$  as the start position of  $T_{i,m}$  subsequence.

For each subsequence of a time series, we can compute its distance to all subsequences of the same length in the same time series. This is called a distance profile.

**Definition 2.3.** Given a query subsequence  $T_{i,m}$ , a distance profile  $D_i$  of  $T_{i,m}$  in the time series  $T$  is a vector of the

distances between  $T_{i,m}$  and each subsequence of length  $m$  in time series  $T$ . Formally,  $D_i = \langle d_{i,1}, \dots, d_{i,n-m+1} \rangle$ , where  $d_{i,j}$  is the distance between  $T_{i,m}$  and  $T_{j,m}$ .

Note that the term *distance* in Definition 2.3 does not refer to the mathematical definition of *distance*. It only gives a measure on the difference between two subsequences. For instance the z-normalized Euclidean distance does not satisfy the (mathematical) axioms of a distance. A *matrix profile* is a vector that represents the minimum distance between each subsequence and all other subsequences of a time series  $T$ .

**Definition 2.4.** Given a subsequence length  $m$ , the *matrix profile* of a time series  $T$  is a vector  $P = \langle p_1, \dots, p_{n-m+1} \rangle$  such that  $p_i$  is the minimum distance between the subsequence  $T_{i,m}$  and all other subsequence of  $T$ , for  $1 < i < n - m + 1$ . In other words,  $p_i = \min(D_i)$ , i.e.,  $p_i$  is the minimum value in the distance profile of  $T_{i,m}$ .

We are interested in the efficient computation of matrix profile using following three different distance measures: 1) Euclidean distance; 2) p-norm distance that is a generalization of Euclidean distance; 3) z-normalized Euclidean distance.

**Definition 2.5.** The *Euclidean distance* between two subsequences  $T_{i,m}$  and  $T_{j,m}$  is defined as:

$$D_{i,j} = \sqrt{\sum_{l=0}^{m-1} (t_{i+l} - t_{j+l})^2} \quad (1)$$

In this paper, sometimes we call the Euclidean distance as *non-normalized (classical) Euclidean distance*.

**Definition 2.6.** Let  $p > 1$  be a positive integer, then the *p-norm distance* between two subsequences  $T_{i,m}$  and  $T_{j,m}$  is defined as:

$$DP_{i,j} = \sqrt[p]{\sum_{l=0}^{m-1} (t_{i+l} - t_{j+l})^p} \quad (2)$$

The z-normalized Euclidean distance between two subsequences is defined as follows.

**Definition 2.7.** Let  $\mu_i$  and  $\mu_j$  be the mean of the values in two subsequences  $T_{i,m}$  and  $T_{j,m}$  respectively. Also, let  $\sigma_i$  and  $\sigma_j$  be the standard deviation of the values in  $T_{i,m}$  and  $T_{j,m}$  respectively. Then, the *z-normalized Euclidean distance* between  $T_{i,m}$  and  $T_{j,m}$  is defined as:

$$DZ_{i,j} = \sqrt{\sum_{l=0}^{m-1} \left( \frac{t_{i+l} - \mu_i}{\sigma_i} - \frac{t_{j+l} - \mu_j}{\sigma_j} \right)^2} \quad (3)$$

A shapelet is a subsequences that can maximally represent the class of a time series. The matrix profile can be used for shapelet detection (see Section SM: .2). Let us define the *joint matrix profile* of two time series that is needed for explaining the shapelet discovery using matrix profile.

**Definition 2.8.** Let  $m$  be the subsequence length, and  $A$  and  $B$  be two time series of length  $n$ . The *joint matrix profile* of  $A$  with  $B$  is a vector  $P_{AB} = \langle p_1, \dots, p_{n-m+1} \rangle$  such that  $p_i$  is the minimum distance between the subsequence  $A_{i,m}$  and

all subsequence of time series  $B$ .

### 3 AAMP

In this section, we propose the AAMP algorithm for computing matrix profile by using the Euclidean distance. At first, we present the formula for incremental computation of the Euclidean distance and then propose the AAMP algorithm which uses this formula for computing matrix profile.

#### 3.1 Incremental Computation of Euclidean Distance

Here, we present a formula that allows us to compute the Euclidean distance between two subsequences  $T_{i,m}$  and  $T_{j,m}$  based on the Euclidean distance of subsequences  $T_{i-1,m}$  and  $T_{j-1,m}$ . The formula is presented by the following lemma.

**Lemma 1.** Let  $D_{i,j}$  be the Euclidean distance between two subsequences  $T_{i,m}$  and  $T_{j,m}$ . Let  $D_{i-1,j-1}$  be the Euclidean distance between two subsequences  $T_{i-1,m}$  and  $T_{j-1,m}$ . Then  $D_{i,j}$  can be computed as:

$$D_{i,j} = \sqrt{D_{i-1,j-1}^2 - (t_{i-1} - t_{j-1})^2 + (t_{i+m-1} - t_{j+m-1})^2} \quad (4)$$

**Proof.** Let  $T_{i,m} = \langle t_i, t_{i+1}, \dots, t_{i+m-1} \rangle$  and  $T_{j,m} = \langle t_j, t_{j+1}, \dots, t_{j+m-1} \rangle$ . Then the square of the Euclidean distance between  $T_{i,m}$  and  $T_{j,m}$  is computed as:

$$D_{i,j}^2 = \sum_{l=0}^{m-1} (t_{i+l} - t_{j+l})^2 \quad (5)$$

And the square of the Euclidean distance between  $T_{i-1,m}$  and  $T_{j-1,m}$  is:

$$D_{i-1,j-1}^2 = \sum_{l=0}^{m-1} (t_{i-1+l} - t_{j-1+l})^2 \quad (6)$$

By comparing Equations (5) and (6), we have:

$$D_{i,j}^2 = D_{i-1,j-1}^2 - (t_{i-1} - t_{j-1})^2 + (t_{i+m-1} - t_{j+m-1})^2 \quad (7)$$

Thus, we have:

$$D_{i,j} = \sqrt{D_{i-1,j-1}^2 - (t_{i-1} - t_{j-1})^2 + (t_{i+m-1} - t_{j+m-1})^2} \quad (8)$$

By using the above equation, we can compute the Euclidean distance  $D_{i,j}$  by using the distance  $D_{i-1,j-1}$  in  $O(1)$ .

#### 3.2 Algorithm

The main idea behind AAMP is that for computing the distance between subsequences, it uses *diagonal sliding windows*, such that in each sliding window, the Euclidean distance is computed only between the subsequences that have a precise difference in their *starting positions*. These sliding windows allow us to use Equation (4) for efficient distance computation.

Algorithm 1 shows the pseudo-code of AAMP (for now, ignore the violet colored lines). Initially, the algorithm sets all

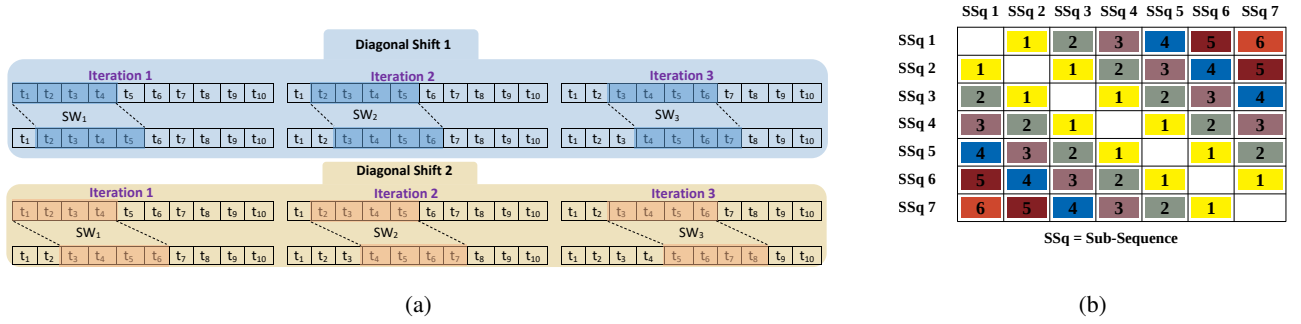


Figure 2: a) Example of AAMP execution on a time series of length  $n = 10$ , and with subsequence length  $m = 4$ . The total number of subsequences is  $n - m + 1 = 10 - 4 + 1 = 7$ . In iteration  $k$ , the distances between the subsequences that are  $k$  positions apart from each other are computed. The first distance in each iteration is computed using the normal Euclidean distance function in  $O(m)$ , and the other distances are computed incrementally in a constant time. b) The subsequences are arranged in a matrix to better understand the functioning of AAMP algorithm. By looking at the cells of the matrix, we can see in which iteration, the distance of two subsequences is calculated. Different iterations are represented by different colors.

values of the *matrix profile* array to infinity (i.e., maximum distance) and the *matrix profile index* array to 1. Then, it performs  $n - m$  iterations using a variable  $k$  ( $1 \leq k \leq n - m$ ). In each iteration of  $k$ , the algorithm calculates distance between  $i^{th}$  subsequence (i.e.  $T_{i,m}$ ) and the subsequence which is  $k$  positions apart from it, i.e.,  $T_{i+k,m+k}$ . The value of  $i$  is primarily taken as 1 then it iterates from 2 to  $n - m + 1 - k$  values in Line 13.

In each iteration  $k$ , AAMP firstly computes the Euclidean distance of the  $1^{st}$  subsequence of the time series, i.e.,  $T_{1,m}$ , with the one that starts at  $k$  positions from it, i.e. subsequence  $T_{k+1,m+k}$ . The first distance computation is done using the classical formula of Euclidean distance, i.e. using Equation (1) (see Line 6). Then, in a sliding window, the algorithm incrementally computes the distance of other subsequences with the subsequences that are  $k$  position apart from them (i.e.  $2^{nd}$  with  $3^{rd}$  subsequence,  $3^{rd}$  with  $4^{th}$  subsequence etc.), and this is done in  $O(1)$  time. If the computed distance is smaller than the existing distance value in the matrix profile array  $P$ , then the smaller distance is saved in the matrix profile along with its index (see Lines 7 – 12 and 15 – 20). Note that, we use the property that the distance between  $i^{th}$  and  $j^{th}$  subsequences is equal to the distance between  $j^{th}$  and  $i^{th}$  subsequences; i.e.  $dist_{i,j} = dist_{j,i}$  (see Lines 8 – 9 & 11 – 12; and Lines 16 – 17 & 19 – 20). In AAMP, we use square of the Euclidean distances for comparing the distances of different subsequences (see Lines 6 and 14), and at the end of the algorithm, square of these distances is replaced by taking the *sqr*t to obtain the real distances in the matrix profile (see Line 22). This reduces the number of *sqr*t operations done during the execution of the algorithm.

**Example 1.** Figure 2a shows an example of executing AAMP over a time series of length  $n = 10$  and for subsequences of length  $m = 4$ . In iteration 1, the first Euclidean distance is calculated between  $T_{1,m}$  and  $T_{2,m}$  and the sliding window  $SW_1$ . Then the sliding window moves to the next subsequences (i.e. sliding window  $SW_2$ ), and incrementally computes the distance between  $T_{2,m}$  and  $T_{3,m}$  by using the Equation (4) in  $O(1)$  time. Then, the sliding window moves to

the next subsequences and computes their distances, i.e.,  $T_{3,m}$  and  $T_{4,m}$ . This distances computation process continues for all the subsequence pairs, which are 1 element/index apart from each other's starting positions. For iteration 1, the distances computed between all the subsequence pairs are marked by yellow color in the matrix shown in Fig. 2b.

In iteration 2, the Euclidean distance is computed between each subsequence and the one which is 2 elements/indexes apart (follow the bottom image in Fig. 2a). Thus, we calculate the distances between subsequence 1 & 3 followed by the distance between subsequence 2 and 4 etc. (shown by black colored cells in the matrix of Fig. 2b). Note that, in each iteration the first distance is computed using the classical Euclidean distance formula and the other distances are computed by using the incremental formula.

By looking at the cells of the matrix in Fig. 2b, we can see in which iteration, the distance of two subsequences is calculated. Different iterations are represented by different colors.

### 3.3 Complexity Analysis

The AAMP algorithm contains two loops. In the  $1^{st}$  loop (Line 6), the distance between  $T_{1,m}$  and  $T_{k,m}$  is computed by using the normal Euclidean distance function in  $O(m)$  time, thus in total, Line 6 is executed in  $O(m \times (n - m))$ . In the nested loop (Lines 13 – 20), all operations are done in  $O(1)$ , so in total these operations are done in  $O((n - m)^2)$ . Thus, the time complexity is  $O((n - m)^2) + m \times (n - m)$  which is equivalent of  $O(n \times (n - m))$ . If  $n \gg m$ , then the time complexity of AAMP can be written as  $O(n^2)$ . But, if  $m$  is very close to  $n$ , i.e.,  $m = n - c$  for any small constant  $c$ , then the time complexity is  $O(n)$ . The space needed for our algorithm is only the array of matrix profile and some simple variables. Thus, the space complexity is  $O(n)$ .

### 3.4 Extension of AAMP to p-Norm Distance

In this section, we extend the AAMP algorithm to the p-norm distance that is a more general form of distance computation than Euclidean distance formula. The p-norm functions are



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**Algorithm 1:** AAMP algorithm: matrix profile with Euclidean distance
 

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**Input:**  $T$ : time series;  $n$ : length of time series;  $m$ : subsequence length

**Output:**  $P$ : Matrix profile;  $I$ : Matrix profile Indexes;

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1 begin
2   for  $i=1$  to  $n-m+1$  do
3      $P[i] = \infty$   $\triangleright$  initialize the matrix profile
4      $I[i] = 1$   $\triangleright$  initialize the matrix profile indexes
5   for  $k=1$  to  $n-m$  do
6      $dist = \text{EuclideanDistance}(T_{1:m}, T_{k+1:m+k})^2$   $\triangleright$ 
       compute square of the distance between 1st i.e.
        $T_{1:m}$  and  $(k+1)^{th}$  i.e.  $T_{k+1:m+k}$  subsequences
7     if  $dist < P[1]$  then
8        $P[1] = dist$ 
9        $I[1] = k + 1$ ;
10    if  $dist < P[k+1]$  then
11       $P[k+1] = dist$ 
12       $I[k+1] = 1$ 
13    // if  $k+1 == n-m+1$  then
14    //  $B[1] = dist$   $\triangleright$  if we are computing the
15    distance between 1st and last sub-sequence
16    for  $i=2$  to  $(n-m+1-k)$  do
17       $dist =$ 
18       $(dist - (t_{i-1} - t_{i-1+k})^2 + (t_{i+m-1} - t_{i+m+k-1})^2)$ 
19      if  $dist < P[i]$  then
20         $P[i] = dist$ 
21         $I[i] = k + i$ 
22      if  $dist < P[i+k]$  then
23         $P[i+k] = dist$ 
24         $I[i+k] = i$ 
25      // if  $i+k == n-m+1$  then
26      //  $B[1,1] = dist$   $\triangleright$  if we are computing the
27      distance with last sub-sequence
28    for  $i=1$  to  $n-m+1$  do
29       $P[i] = \sqrt{P[i]}$ 

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used in *Lebesgue spaces* ( $L^p$ ), which are useful in data analysis in physics, statistics, finance, engineering, etc.

Let  $T_{i,m}$  and  $T_{j,m}$  be two time series subsequences, then their  $p$ -norm distance (for  $p > 1$ ) is defined as:

$$DP_{i,j} = \sqrt[p]{\sum_{l=0}^{m-1} (t_{i+l} - t_{j+l})^p} \quad (9)$$

Notice that the Euclidean distance is a special case of  $p$ -norm with  $p = 2$ . The following lemma gives an incremental formula for computing  $PNORM_{i,j}$ .

**Lemma 2.** Let  $DP_{i,j}$  be the  $p$ -norm distance of subsequences  $T_{i,m}$  and  $T_{j,m}$ . Then,  $DP_{i,j}$  can be computed by using the  $p$ -norm distance of subsequences  $T_{i-1,m}$  and  $T_{j-1,m}$ , denoted by  $DP_{i-1,j-1}$ , as:

$$DP_{i,j} = \sqrt[p]{(DP_{i-1,j-1})^p - (t_{i-1} - t_{j-1})^p + (t_{i+m-1} - t_{j+m-1})^p}$$

**Proof.** The proof can be easily done in a similar way as that of Lemma 1. Using Lemma 2, we can modify the AAMP algorithm to compute the matrix profile with the  $p$ -norm distance. This can be done just by modifying two lines in Algorithm 1: i) in Line 6 we replace the Euclidean distance with  $p$ -norm distance between the subsequences; i.e.  $T_{1,m}$  and  $T_{k,m}$ ; ii) in Line 14, we incrementally compute the  $p$ -norm distance using Lemma 2.

The time and space complexity of the AAMP algorithm for  $p$ -norm is the same as that of AAMP with the Euclidean distance.

## 4 ACAMP: MATRIX PROFILE FOR Z-NORMALIZED EUCLIDEAN DISTANCE

In this section, we propose an algorithm, called ACAMP, that computes matrix profile based on the  $z$ -normalized Euclidean distance and using the similar principle as AAMP, i.e., incremental distance computation by using diagonal sliding windows.

### 4.1 Incremental Computation of Z-Normalized Euclidean Distance

Let us now explain how ACAMP computes the  $z$ -normalized Euclidean distance incrementally. Let  $T_{i,m} = \langle t_i, \dots, t_{i+m-1} \rangle$  and  $T_{j,m} = \langle t_j, \dots, t_{j+m-1} \rangle$  be two subsequences of a time series  $T$ . In ACAMP, we compute the  $z$ -normalized Euclidean distance between  $T_{i,m}$  and  $T_{j,m}$  by using the following five variables:

- $A_i = \sum_{l=0}^{m-1} t_{i+l}$ : the sum of the values in  $T_{i,m}$ ;
- $B_j = \sum_{l=0}^{m-1} t_{j+l}$ : the sum of the values in  $T_{j,m}$ ;
- $A_i^2 = \sum_{l=0}^{m-1} t_{i+l}^2$ : the sum of the square of values in  $T_{i,m}$ ;
- $B_j^2 = \sum_{l=0}^{m-1} t_{j+l}^2$ : the sum of the square of values in  $T_{j,m}$ ;
- $C_{i,j} = \sum_{l=0}^{m-1} t_{i+l} \times t_{j+l}$ : the product of values of  $T_{i,m}$  and  $T_{j,m}$ .

Note that all above variables can be computed incrementally, when moving a sliding window from  $T_{i,m}$  to  $T_{i+1,m}$ . Given these variables, the  $z$ -normalized Euclidean distance between two subsequences  $T_{i,m}$  and  $T_{j,m}$  can be computed using the formula given by the following lemma.

**Lemma 3.** Let  $DZ_{i,j}$  be the  $z$ -normalized distance of subsequences  $T_{i,m}$  and  $T_{j,m}$ . Then,  $DZ_{i,j}$  can be computed as:

$$DZ_{i,j} = \sqrt{2m \left( 1 - \frac{C_{i,j} - \frac{1}{m} A_i B_j}{\sqrt{(A_i - \frac{1}{m} A_i^2) (B_j - \frac{1}{m} B_j^2)}} \right)} \quad (10)$$

The proof of Lemma 3 can be seen in Section SM: .1 of the *Supplementary Materials*.

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**Algorithm 2:** ACAMP algorithm: matrix profile calculation with z-normalized Euclidean distance

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**Input:** T: time series; n: length of time series; m: subsequence length

**Output:** P: Matrix profile; I: Matrix profile Indexes;  
begin

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for i=1 to n-m+1 do
  P[i] = ∞; I[i] = 1
  for k=1 to n-m do
    A =  $\sum_{l=0}^{m-1} t_{1+l}$  ▷ sum of the values in  $T_{1,m}$ 
    B =  $\sum_{l=0}^{m-1} t_{1+k+l}$  ▷ sum of the values in  $T_{1+k,m}$ 
    A =  $\sum_{l=0}^{m-1} t_{1+l}^2$  ▷ sum of the square of values in  $T_{1,m}$ 
    B =  $\sum_{l=0}^{m-1} t_{1+k+l}^2$  ▷ sum of the square of values in  $T_{1+k,m}$ 
    C =  $\sum_{l=0}^{m-1} t_{1+l} t_{1+k+l}$  ▷ product of values of  $T_{1,m}$  and  $T_{1+k,m}$ 
    dist =  $2m \left( 1 - \frac{C - \frac{1}{m}AB}{\sqrt{(A - \frac{1}{m}A^2)(B - \frac{1}{m}B^2)}} \right)$  ▷ compute the square of z-normalized distance
    if dist < P[1] then
      P[1] = dist; I[1] = k + 1;
    if dist < P[k + 1] then
      P[k + 1] = dist; I[k + 1] = 1
    for i=2 to n - m + 1 - k do
      A = A -  $t_{i-1}$  +  $t_{i+m-1}$ ;
      B = B -  $t_{i-1+k}$  +  $t_{i+m+k-1}$ ;
      A = A -  $t_{i-1}^2$  +  $t_{i+m-1}^2$ ;
      B = B -  $t_{i-1+k}^2$  +  $t_{i+m+k-1}^2$ ;
      C = C -  $t_{i-1} \times t_{i-1+k}$  +  $t_{i+m-1} \times t_{i+m+k-1}$ ;
      dist =  $2m \left( 1 - \frac{C - \frac{1}{m}AB}{\sqrt{(A - \frac{1}{m}A^2)(B - \frac{1}{m}B^2)}} \right)$ 
      if dist < P[i] then
        P[i] = dist; I[i] = k + i
      if dist < P[i + k] then
        P[k + i] = dist; I[k + i] = i
  for i=1 to n do
    P[i] =  $\sqrt{P[i]}$  ▷ compute the z-normalized distance from its square

```

---

## 4.2 Algorithm

The pseudo-code of ACAMP is shown in Algorithm 2. In Line 4 in a loop,  $k$  is iterated from 1 to  $n - m$ , and in each iteration the z-normalized Euclidean distance is calculated between the subsequences which are  $k$  points far from each other in the time series (Lines 5 to 14). In each iteration, the distances are computed by using the formula of Equation 10 that uses the five variables *i.e.*,  $A$ ,  $B$ ,  $A$ ,  $B$  and  $C$ . For each iteration of  $k$ , the distance between two initial subsequence is calculated (*i.e.* the distance between  $T_{1,m}$  and  $T_{1+k,m}$ ), by using the five variables in  $O(m)$  time (see Lines 5 to 10).

For the other subsequences, these variables and the distance are incrementally computed in  $O(1)$  time. Note that in the algorithm, for performance reasons we compare the square of the z-normalized Euclidean distance of the subsequences (Line 10 and 21). At the end of the algorithm (Lines 26 to 27), in a loop we convert the square distances to the real distances.

The time and space complexity of ACAMP algorithm is same as that of AAMP algorithm, described in Section 3.3.

## 4.3 More Optimization of ACAMP

In the following section, we propose several optimizations for the ACAMP Algorithm.

One possible optimization is to move the first calculation of variables  $A$ ,  $B$ , and  $C$  (actually done in Lines 7 to 10) before the loop (*i.e.*, before Line 4). By doing this, firstly, we can avoid the redundant computation of  $A$  &  $B$  and  $C$ . Then the calculation of distance between the 1<sup>st</sup> and all other subsequences can be pre-computed. Hence, we would just need to incrementally update these variables in the loop (Lines 16 – 20).

We can further optimize ACAMP by not comparing the square of z-normalized distance in Lines 15, 17, 26 and 28 in Algorithm 2, but by comparing  $F_{i,j}$  defined as follows:

$$F_{i,j} = \frac{(A_i B_j - m C_{i,j}) \times |A_i B_j - m C_{i,j}|}{(A_i - \frac{1}{m} A_i^2)(B_j - \frac{1}{m} B_j^2)}, \quad (11)$$

We can easily show that  $DZ_{i,j} > DZ_{i,k}$  if and only if  $F_{i,j} > F_{i,k}$ . In the formula of  $F_{i,j}$ , there is no square root operation, and its computation takes less time than that of  $DZ_{i,j}$ . Thus, for comparing the z-normalized Euclidean distance of subsequences, we can simply compare their  $F_{i,j}$ . Then in Line 21 of the algorithm, the following equation can be used for computing the z-normalized Euclidean distance  $DZ_{i,j}$  from  $F_{i,j}$ :

$$DZ_{i,j} = 2m + 2 \times \text{sign}(F_{i,j}) \times \sqrt{|F_{i,j}|} \quad (12)$$

## 4.4 AAMP for streaming data

After discussing about *offline* version of AAMP algorithm, here in this section we will talk about AAMP algorithm for streaming data. The original concept of matrix profile on streaming data is proposed by Yeh et.al [10]. We apply the similar idea on AAMP to handle real time streaming data.

In some situations, it is needed to build the matrix profile incrementally based on the feed of real-time data. It is highly useful to continuously upgrade the matrix profile for new data by adjusting the existing matrix profile. In Algorithm 3, we have illustrated the proposed approach to handle streaming data. In case of *streaming* algorithm, it is considered that the data points arrives one-by-one in a sequential manner. This algorithm is made on the foundation of Algorithm 1 which is designed to work in sequential order.

## 5 PERFORMANCE EVALUATION

In this section, we compare the execution time of our algorithms AAMP and ACAMP with the state-of-the-art matrix

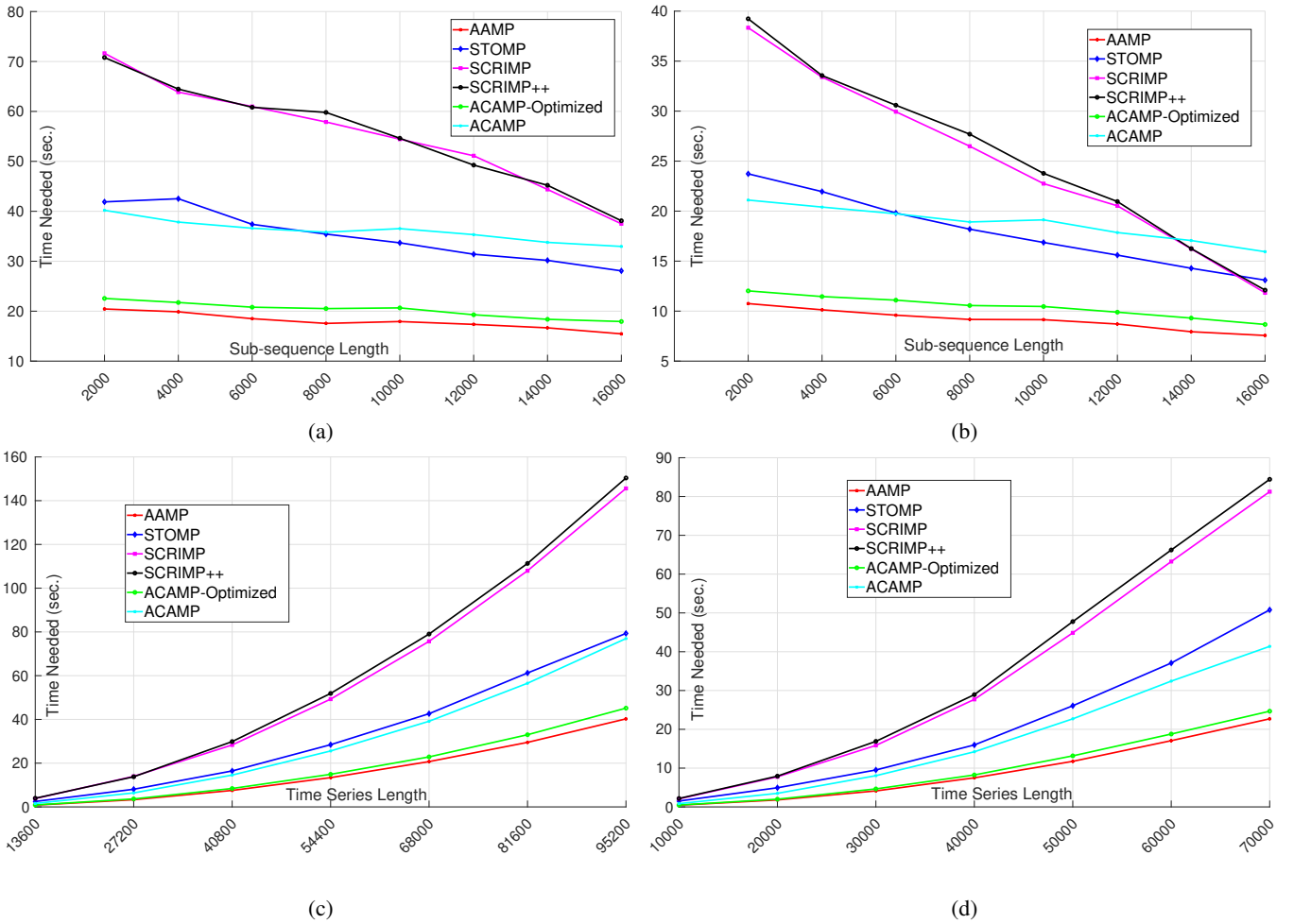


Figure 3: The execution times of six algorithms with increasing the subsequence length ( $m$ ): a) Execution time of the six algorithms on a time series of length 68000 (protein dataset). b) Execution time of the six algorithms on a time series of length 50000 (sheep dataset). The execution time of six algorithms are plotted with the increase of time series length ( $n$ ): c) Execution time of the six algorithms on variable time series length (protein dataset) with  $m = 256$ . d) execution time of the six algorithms on variable time series length (sheep dataset) with  $m = 256$ .

profile algorithms STOMP, SCRIMP and SCRIMP++ [8]. We also evaluate the optimized version of ACAMP (using the optimizations proposed in Section 4.3) called as *ACAMP-Optimized*. We first describe the experimental setup, the datasets used for the performance evaluation and then present the results of the experiments.

## 5.1 Setup

We implemented our algorithms in MATLAB<sup>1</sup>. For STOMP<sup>2</sup>, SCRIMP<sup>3</sup> and Scrimp++<sup>4</sup>, we used the Matlab code available from [11] using the step size of PreSCRIMP = 0.25. The evaluation and tests were carried out on a off-the-shelf computer with Intel (®)Core(TM)™i7-8850H CPU @ 2.60 GHz × 8 processors, on Ubuntu 18.04 LTS and 32 GB RAM with the R2019A version of Matlab.

<sup>1</sup>Our code and data are accessible at: <https://sites.google.com/view/aamp-and-acamp/home>

<sup>2</sup><https://sites.google.com/view/mstamp/>

<sup>3</sup><https://www.cs.ucr.edu/~eamonn/MatrixProfile.html>

<sup>4</sup><https://sites.google.com/site/scrimplusplus/>

### 5.1.1 Datasets

The first dataset corresponds to spectrums of 680 dimensions, representing a protein rate measured on 10 different products: rapeseed (CLZ), corn gluten (CNG), sun flower seed (SFG), grass silage (EHH), full fat soya (FFS), wheat (FRG), sun flower seed (SFG), animal feed (ANF), soyameal set(representrs and whey (MPW). The complete dataset represents 4075 time series of 680 values (680 elements per time series).

The second real world dataset corresponds to time series of 500 dimensions which have been measured by attaching accelerometer at the neck of some sheep. Accelerometers captured 3-axial acceleration at a constant rate of 100Hz. The complete dataset represents 8532 time series of 500 values.

We have also done experiments on several real world datasets from the UCR Time Series Classification Archive [12], such as CinCECGTorso, EOGVerticalSigna, EOGHorizontalSignal, ArrowHead, etc.

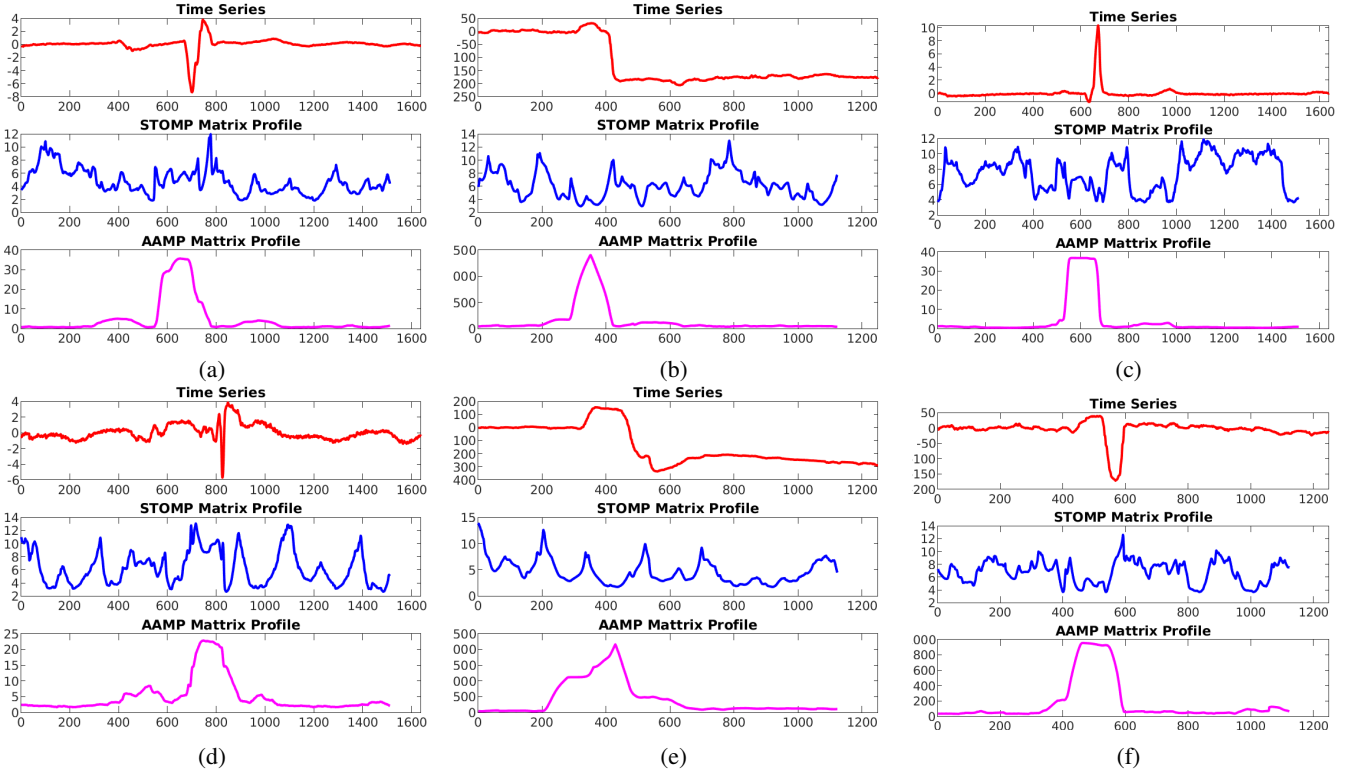


Figure 4: (a) **Top:** Time series from **CinCECGTorso** dataset. The discord is visible in it. **Middle:** the matrix profile, obtained by STOMP algorithm; **Bottom:** The matrix profile, obtained by AAMP algorithm. (b) Time series from **EOGVerticalSignal** dataset and corresponding matrix profile by STOMP and AAMP algorithms. (c) Time series from **CinCECGTorso** dataset (d) Time series from **CinCECGTorso** dataset (e) Time series from **EOGHorizontalSignal** dataset (f) Time series from **EOGVerticalSignal** dataset

## 5.2 Execution time

The first experiment on execution time is performed by keeping the time series length ( $n$ ) fixed, and varying the subsequence length ( $m$ ; plotted along  $X$ -axis). For this experiment, we used the protein and sheep datasets. For the protein dataset, we have used the first 100 time series and concatenated them to generate a single time series of 68000 ( $100 \times 680$ ) elements. In the case of the sheep dataset, we took the first 100 time series and concatenated them to generate a single time series of 50000 ( $100 \times 500$ ) elements).

The execution times of the six algorithms are plotted in Fig. 3a and 3b using the protein and sheep datasets respectively. As seen, the execution time of all algorithms decreases with increasing subsequence length ( $m$ ). On both databases, AAMP and ACAMP-Optimized outperform other algorithms. Until  $m = 8000$ , ACAMP is better than STOMP, but for higher values STOMP behaves better. For very high values of  $m$  (e.g., when  $m$  is close to  $n$ ), the execution time of all algorithms gets almost the same, because in these cases there are few subsequences in the time series. Notice that in practice the subsequence size is not very high (e.g., less than 4000), and in these cases the performance of AAMP and ACAMP-Optimized is significantly better than the state-of-the-art algorithms.

The second experiment is performed by keeping a fixed subsequence length  $m = 256$  (in accordance with the experiments in related work, e.g. [1] and [2]), and varying the length of

time series, i.e.,  $n$ . The results for the two datasets are shown in Fig. 3c and 3d. We observe that the execution time of all algorithms increases linearly with the increase of time series length. AAMP and ACAMP-Optimized algorithms outperform the state-of-the-art algorithms, and their performance difference increases significantly by increasing  $n$ . Thus, the bigger is the time series, the higher is the performance gain of our AAMP and ACAMP-Optimized algorithms.

## 5.3 Discord discovery

The AAMP and ACAMP algorithms are capable to detect the discords (anomalies) from the time series like other matrix profile based algorithms such as STOMP, SCRIMP and SCRIMP++. The matrix profile generated by ACAMP is exactly the same as the one generated by STOMP, SCRIMP and SCRIMP++, as all of these techniques use the  $z$ -normalized Euclidean distance. But, AAMP uses non-normalized Euclidean distance, thus the detected discords can be different. Hence, depending on the user requirements and the domains of applications, the techniques from both groups can be useful. An example is shown in Fig. 5a by using two real ECG datasets [2]. The visible discords (of subsequence length 50) are marked by red color in these time series. It can be seen that the anomaly or unusual pattern existing in the first time series can be detected by AAMP, whereas SCRIMP++ (or any of the other  $z$ -normalized based algorithm) was unable to



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**Algorithm 3:** STREAMING\_AAMP( $T, t, m, P_T, I_T, \mathcal{B}$ )

---

**Input:**  $T$ ; new data point ( $t$ );  $m$ ; calculated matrix profile ( $P$ ); associated index profile ( $I$ ); dot product vector ( $\mathcal{C}$ )

**Output:** The updated matrix profile ( $P^{new}$ ); updated index profile  $I^{new}$  corresponding to incremented time series ( $T^{stream} = [T, t]$ );

```

1  $Idx_T \leftarrow (n - m + 1)$ ;  $T \leftarrow [T, t]$ ;  $\mathbb{Z} \leftarrow \frac{m}{2}$ 
2  $P \leftarrow [P, 0]$ ;  $I \leftarrow [I, 0]$ 
3  $nSq \leftarrow T[(Idx_T + 1) : (n + 1)]$ 
4  $dist = Euc\_Distance(T_{1:m}, nSq)$ 
5 if  $dist < P[1]$  then
6    $P[1] = dist$ 
7    $I[1] = k + 1$ ;
8 if  $dist < P[k + 1]$  then
9    $P[k + 1] = dist$ 
10   $I[k + 1] = 1$ 
11  $\mathcal{B}[1] = dist$ 
12 for  $i=2$  to  $Idx_T$  do
13    $dist =$ 
      $\mathcal{B}[i] - (T[i - 1] - T[Idx_T])^2 + (T[i + m - 1] - T[Idx_T + m + 1])^2$ 
14    $\mathbb{G} \leftarrow Idx_T + 1 - i \triangleright \text{gap between subsequences}$ 
15   if  $\mathbb{G} > \mathbb{Z}$  then
16      $Flag = True$ 
17   if  $dist < P[i]$  &  $Flag == True$  then
18      $P[i] = dist$ 
19      $I[i] = Idx_T + 1$ 
20   if  $dist < P[Idx_T + 1]$  &  $Flag == True$  then
21      $P[Idx_T + 1] = dist$ 
22      $I[Idx_T + 1] = i$ 
23    $\mathcal{B}[1, i] = dist$ 
24 for  $i=1$  to  $Idx_T$  do
25    $P[i] = \sqrt{P[i]}$ 
26 return  $P_T, I_T, \mathcal{B}$ 

```

---

detect it. The reason is due to  $z$ -normalization by *SCRIMP++*. *AAMP* is able to take into account the range of values of the matches with respect to the range of values of the given subsequence. This is why *AAMP* does not find a close match for this unusual subsequence (it's range of values is mostly less than  $-2$ ). In the second time series (top right image in Fig. 5a) another similar situation is presented where *AAMP* was able to correctly detect the discord but *SCRIMP++* failed to locate it.

Figure 4 shows examples of time series from different UCR datasets, and the matrix profiles generated by *AAMP* and *STOMP* algorithms for the time series. In each time series there is a visible anomaly (an unusual pattern), which is clearly detected by the *AAMP* algorithm, i.e., as high value point in the matrix profile. But, in the matrix profile generated by the *STOMP* algorithm, the anomalies are not visible or hardly

distinguishable from other subsequences.

From the above mentioned experimental evaluations, we can conclude that our proposed *AAMP* algorithm shows better performance in detecting anomalies (and also motifs) in certain domain of applications, compared to the  $z$ -normalization based algorithms such as *STOMP* and *SCRIMP++*. However, in certain domain of applications,  $z$ -normalization based algorithms are more useful. Then in such cases, it is better to use the *ACAMP-optimized* algorithm which has lower execution time than the state-of-the-art techniques, i.e. *STOMP*, *SCRIMP* and *SCRIMP++*, and is able to compute exactly the same matrix profile as the one computed by these algorithms.

## 5.4 Pros and Cons of Z-normalized over Non-normalized distance

There are pros & cons of both the  $z$ -normalized and non-normalized Euclidean distances. In this section, we discuss them.

### 5.4.1 Range of the matches

The techniques such as *STOMP*, *SCRIMP*, *SCRIMP++* and *ACAMP* are able to find the matches without taking into account the range of values of the matches. These techniques only consider the shape of the subsequences (because of  $z$ -normalization), whereas a non-normalized Euclidean distance based technique, e.g., *AAMP*, can find the matches from the same range of values as the given subsequence while taking into account its shape as well. Some examples of the matches obtained by *STOMP* and *AAMP* are shown in Fig. 1b. Hence, the  $z$ -normalization based techniques are capable of finding similar shape matches from any range of values, and can sometimes provide better matches than non-normalized techniques (see an example in Fig. 6). But when the range of values of the matches is important, then a technique such as *AAMP* is more useful.

### 5.4.2 Zero standard deviation

It is a quite bothersome problem that the  $z$ -normalized distance of two subsequences returns *infinity* when the standard deviation of one of the subsequences is zero (because of division by zero). This can happen when the signal of a subsequence remains stable (i.e., all the values are same in the subsequence). This kind of situation is quite frequent in real datasets, e.g., during the periods when there is no noticeable activities. This problem does not exist for *AAMP* algorithm (based on the non-normalized Euclidean distance), because no division is done in its distance formula. An example is shown in Fig. 5b by using a real seismic dataset where the values of longitudes and heights are plotted. It can be visible that there are several places where the signals remain stable, hence the standard deviation of the subsequences (e.g. of size 50) would become zero. In these cases, we see that *AAMP* is able to detect the outliers by generating the matrix profile (see bottom images of Fig. 5b). But, the  $z$ -normalized based techniques can not find these anomalies.

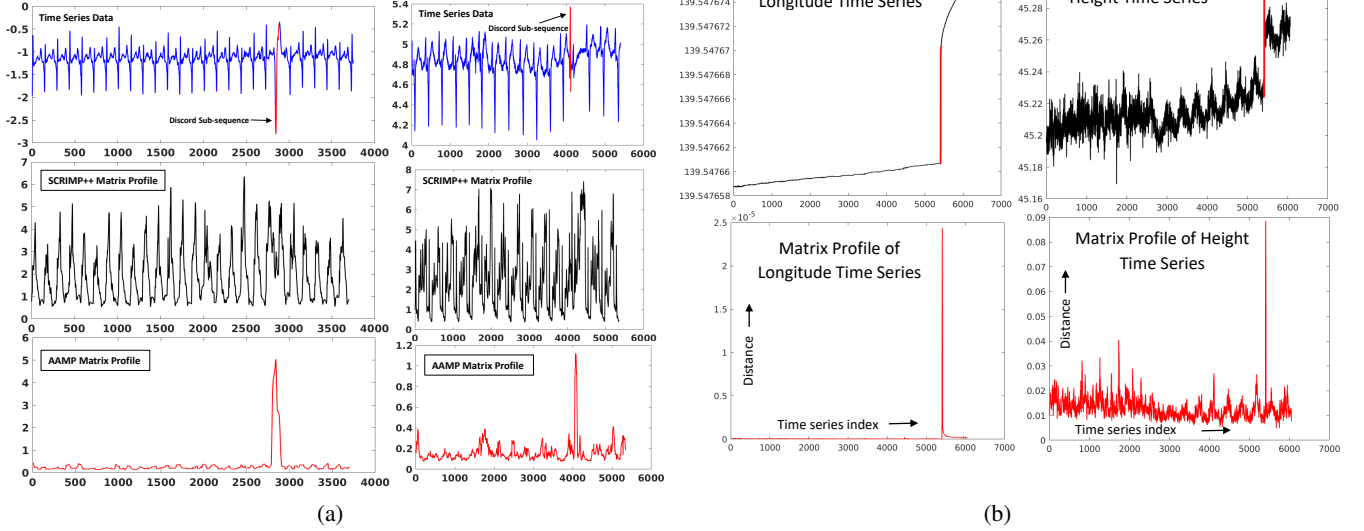


Figure 5: (a) **Top**: two time series from real ECG dataset. The visible discords in these time series are marked by red color. **Middle**: the matrix profile, obtained by SCRIMP++ algorithm; **Bottom**: The matrix profile, obtained by AAMP algorithm. (b) **Top**: the longitude and height time series of Seismic dataset (outliers are marked by red color); **Bottom**: the matrix profile obtained by AAMP algorithm.

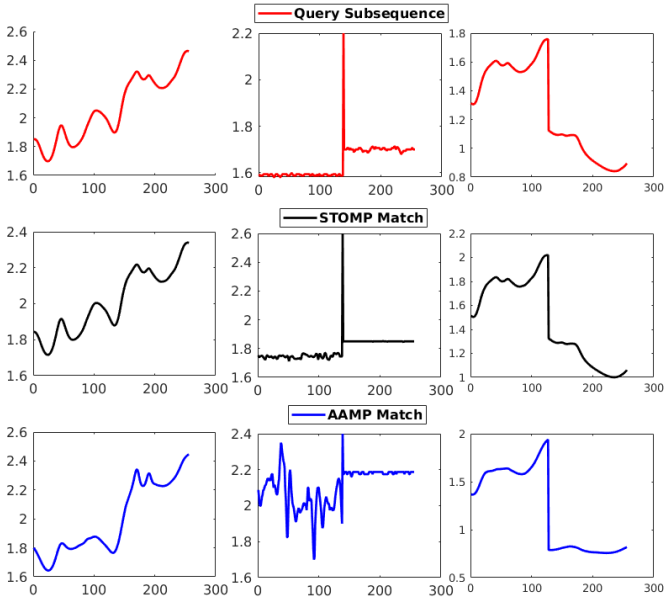


Figure 6: **Top**: First two query sub-sequences from protein and the third sub-sequence from sheep dataset. **Middle**: Better nearest neighbors, obtained by STOMP. **Bottom**: The nearest neighbors, obtained by AAMP algorithm.

## 6 RELATED WORK

Matrix profile has been recently proposed as an efficient technique for detecting motifs and discords in time series [7], [13]. In [1], Yeh et al. introduced the theoretical foundations of matrix profile and proposed a first algorithm, called STAMP for computing the matrix profile over a time series. It uses a similarity search algorithm, called MASS [1] that computes z-normalized Euclidean distance between two subsequences

by using the Fast Fourier Transform (FFT). In [2], Zhu et al. proposed an algorithm, called STOMP, that is faster than STAMP. The STOMP algorithm is similar to STAMP but uses highly optimized nested loop algorithm by applying repeated calculation of distance profiles in the inner loop. However, while STAMP must evaluate the distance profiles in random order (to allow its anytime behavior), STOMP performs an ordered search. STOMP exploits the locality of these searches, and reduces the time complexity by a factor of  $O(\log n)$ . In [8], the authors proposed an extension of STOMP, called SCRIMP++ (also an anytime algorithm), that usually converges faster than STOMP for large subsequence lengths. In [14], Zimmerman et al. proposed an extension of the GPU-based version of STOMP algorithm [2] by exploiting several novel insights for motif discovery envelope, using a scalable framework which can be deployed in commercial cloud based GPU clusters. To the best of our knowledge, almost all matrix profile algorithms have been developed for z-normalized Euclidean distance. In this paper, we proposed AAMP for the non-normalized Euclidean distance. We also proposed two algorithms for the z-normalized case, *i.e.*, ACAMP and ACAMP-Optimized, that are significantly faster than the state of the art algorithms working based on the z-normalized distance. The ACAMP and ACAMP-Optimized algorithms are designed based on an efficient incremental technique that does not need FFT calculations.

## 7 CONCLUSION

In this paper, we addressed the problem of matrix profile computation for a general class of Euclidean distances. We first proposed an efficient algorithm called AAMP for computing matrix profile for the non-normalized Euclidean distance. Then, we extended our algorithm for the p-norm distance,

which is a general form of Euclidean. Then, we proposed ACAMP and its optimized version ACAMP-Optimized that use the same principle as AAMP, but for the case of z-normalized Euclidean distance. Our algorithms are exact, anytime, incrementally maintainable, and can be implemented easily using different languages. To evaluate the performance of our algorithms, we implemented them, and compared their performance with the baseline algorithms such as STOMP, SCRIMP, SCRIMP++. The results show the efficiency of AAMP and ACAMP-Optimized algorithms for computing matrix profile based on z-normalized and non-normalized Euclidean distances. They also illustrate the utility of the matrix profile generated by the AAMP algorithm for detecting anomalies in some datasets, for which the state-of-the-art algorithms are not useful. Overall, we can conclude that both z-normalized and non-normalized based matrix profiles are required for knowledge extraction in a wide range of applications. In this paper, we proposed efficient techniques for both of them.

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## SUPPLEMENTARY MATERIALS (SM)

### SM: .1 Incremental Computation of Z-Normalized Euclidean Distance - Proof

Here, we present the proof of Lemma 3 and Equation 12 that gives an incremental formula for computing matrix profile by using z-normalized Euclidean distance.

**Proof.** Let  $\mu_i$  and  $\mu_j$  be the mean of the values in the sequences  $T_{i,m}$  and  $T_{j,m}$  respectively. Also, let  $\sigma_i$  and  $\sigma_j$  be the standard deviation of the values in the subsequences  $T_{i,m}$  and  $T_{j,m}$  respectively. Then, the z-normalized Euclidean distance between the subsequences  $T_{i,m}$  and  $T_{j,m}$  is defined as:

$$DZ_{i,j} = \sqrt{\sum_{l=1}^{m-1} \left( \frac{t_{i+l} - \mu_i}{\sigma_i} - \frac{t_{j+l} - \mu_j}{\sigma_j} \right)^2} \quad (13)$$

where

$$\mu_i = \frac{1}{m} \sum_{l=0}^{m-1} t_{i+l}; \quad \mu_j = \frac{1}{m} \sum_{l=0}^{m-1} t_{j+l} \quad (14)$$

and

$$\sigma_i = \sqrt{\frac{1}{m} \sum_{l=0}^{m-1} t_{i+l}^2 - (\mu_i)^2}; \quad \sigma_j = \sqrt{\frac{1}{m} \sum_{k=0}^{m-1} t_{j+l}^2 - (\mu_j)^2}. \quad (15)$$

We can write the square of  $DZ$  as following:

$$\begin{aligned} DZ_{i,j}^2 &= \sum_{l=0}^{m-1} \left( \frac{t_{i+l} - \mu_i}{\sigma_i} - \frac{t_{j+l} - \mu_j}{\sigma_j} \right)^2 \\ &= \sum_{l=0}^{m-1} \left( \left( \frac{t_{i+l} - \mu_i}{\sigma_i} \right)^2 - 2 \left( \frac{t_{i+l} - \mu_i}{\sigma_i} \right) \left( \frac{t_{j+l} - \mu_j}{\sigma_j} \right) + \left( \frac{t_{j+l} - \mu_j}{\sigma_j} \right)^2 \right) \\ &= \sum_{l=0}^{m-1} \left( \frac{t_{i+l}^2 - 2t_{i+l}\mu_i + (\mu_i)^2}{(\sigma_i)^2} - 2 \left( \frac{t_{i+l}t_{j+l} - \mu_i t_{j+l} - t_{i+l}\mu_j + \mu_j \mu_i}{\sigma_i \sigma_j} \right) + \frac{t_{j+l}^2 - 2t_{j+l}\mu_j + (\mu_j)^2}{(\sigma_j)^2} \right) \end{aligned} \quad (16)$$

Let

$$\begin{aligned} A_i &= \sum_{l=0}^{m-1} t_{i+l}; \quad B_j = \sum_{l=0}^{m-1} t_{j+l}; \quad \mathbf{A}_i = \sum_{l=0}^{m-1} t_{i+l}^2; \\ \mathbf{B}_j &= \sum_{l=0}^{m-1} t_{j+l}^2; \quad \mathbf{C}_{i,j} = \sum_{l=0}^{m-1} t_{i+l}t_{j+l}. \end{aligned} \quad (17)$$

Then, we have:

$$\begin{aligned} \mu_i &= \frac{1}{m} A_i, \quad \mu_j = \frac{1}{m} B_j \\ (\sigma_i)^2 &= \frac{1}{m} \mathbf{A}_i - \frac{1}{m^2} A_i^2, \quad (\sigma_j)^2 = \frac{1}{m} \mathbf{B}_j - \frac{1}{m^2} B_j^2. \end{aligned} \quad (18)$$

Then, the z-normalized Euclidean distance can be written as:

$$\begin{aligned} DZ_{i,j}^2 &= \sum_{l=0}^{m-1} \left( \frac{t_{i+l}^2 - 2t_{i+l}\mu_i + (\mu_i)^2}{(\sigma_i)^2} - 2 \left( \frac{t_{i+l}t_{j+l} - \mu_i t_{j+l} - t_{i+l}\mu_j + \mu_j \mu_i}{\sigma_i \sigma_j} \right) + \frac{t_{j+l}^2 - 2t_{j+l}\mu_j + (\mu_j)^2}{(\sigma_j)^2} \right) \\ &= \frac{\mathbf{A}_i - 2A_i \frac{1}{m} + \frac{A_i^2}{m}}{\frac{1}{m} \mathbf{A}_i - \frac{1}{m^2} A_i^2} - 2 \times \frac{\mathbf{C}_{i,j} - \frac{2}{m} A_i B_j + \frac{A_i B_j}{m}}{\sqrt{(\frac{1}{m} \mathbf{A}_i - \frac{1}{m^2} A_i^2)(\frac{1}{m} \mathbf{B}_j - \frac{1}{m^2} B_j^2)}} + \frac{\mathbf{B}_j - 2B_j \frac{1}{m} + \frac{B_j^2}{m}}{\frac{1}{m} \mathbf{B}_j - \frac{1}{m^2} B_j^2} \\ &= 2m - 2 \times \frac{m^2 \mathbf{C}_{i,j} - m A_i B_j}{\sqrt{(m \mathbf{A}_i - A_i^2)(m \mathbf{B}_j - B_j^2)}} + \\ &= 2m \left( 1 - \frac{\mathbf{C}_{i,j} - \frac{1}{m} A_i B_j}{\sqrt{(\mathbf{A}_i - \frac{1}{m} A_i^2)(\mathbf{B}_j - \frac{1}{m} B_j^2)}} \right). \end{aligned} \quad (20)$$

As mentioned in Subsection 4.4.1, by taking

$$F_{i,j} = \frac{(A_i B_j - m \mathbf{C}_{i,j}) \times |A_i B_j - m \mathbf{C}_{i,j}|}{(\mathbf{A}_i - \frac{1}{m} A_i^2)(\mathbf{B}_j - \frac{1}{m} B_j^2)}, \quad (21)$$

we have  $DZ_{i,j} = 2m + 2\text{sign}(F_{i,j}) \times \sqrt{|F_{i,j}|}$  and we can use the following equivalence in our algorithm:

$$DZ_{i,j} > DZ_{i,k} \Leftrightarrow F_{i,j} > F_{i,k}.$$

### SM: .2 Shapelet discovery

Here we explain how shapelets can be discovered by matrix profile, and then show examples of shapelets discovered by z-normalized and non-normalized matrix profile algorithms from real datasets.

Consider two time series  $A$  and  $B$ , having class 1 and 0 as their corresponding class labels. We compute the matrix profiles of  $A$  and  $B$ , denoted by  $P_A$  and  $P_B$ , and also their joint matrix profiles  $P_{AB}$  and  $P_{BA}$  (see the definition of *joint matrix profile* in Section 2). The shapelets can be discovered by calculating the difference in heights of  $P_{AB}$  v/s  $P_A$  (or  $P_{BA}$  v/s  $P_B$ ) which is then used as the indicator of good shapelet candidates. The idea here is that if a discriminating pattern is present in  $A$  and not in  $B$ , then it is highly probable that we will see a ‘‘bump’’ at the location of this pattern in  $P_{AB}$  (the same is true for  $P_{BA}$  also). Hence, when an element-wise difference (denoted by  $\mathcal{U} = |P_A - P_{AB}|$ ) is calculated between  $P_A$  and  $P_{AB}$  vectors, we will find high values at those locations where such discriminating patterns (or subsequences) exist in  $A$  (same is true for  $B$ , if we look into  $P_B$  and  $P_{BA}$ ).

Using time series from the ArrowHead dataset of UCR Archive, in Fig. 7 (b) and (d) we show the curve of  $P_A$  and  $P_{AB}$  along with the difference between  $P_A$  and  $P_{AB}$  plotted in Fig. 7 (c) and (e) for the STOMP and AAMP algorithms respectively. A significant difference (quantified by a threshold, shown in dashed line) is observed between the heights of  $P_A$  and  $P_{AB}$  curves, which intrinsically locates the occurrence of good candidate shapelets patterns (detected by STOMP and AAMP algorithms). These difference curves can serve to locate the patterns that only occur in one of the two time series (i.e., good candidates for shapelets). This experiment is performed by randomly choosing 10 time series and concatenating them. The execution times required by AAMP to compute  $P_A$  and  $P_{AB}$  are 0.05 and 0.17 seconds respectively.

Using time series from the ArrowHead dataset of UCR Archive, in Fig. 7 (b) and (d) we show the curve of  $P_{AA}$  and  $P_{AB}$  along with the difference between  $P_{AA}$  and  $P_{AB}$  plotted in Fig. 7 (c) and (e) for the STOMP and AAMP algorithms respectively. A significant difference (quantified by a threshold, shown in dashed line) is observed between the heights of  $P_{AA}$  and  $P_{AB}$  curves, which intrinsically locates the occurrence of good candidate shapelets patterns (detected by STOMP and AAMP algorithms). These difference curves can serve to locate the patterns that only occur in one of the two time series (i.e., good candidates for shapelets). This experiment is performed by randomly choosing 10 time series and concatenating them. The execution times required by



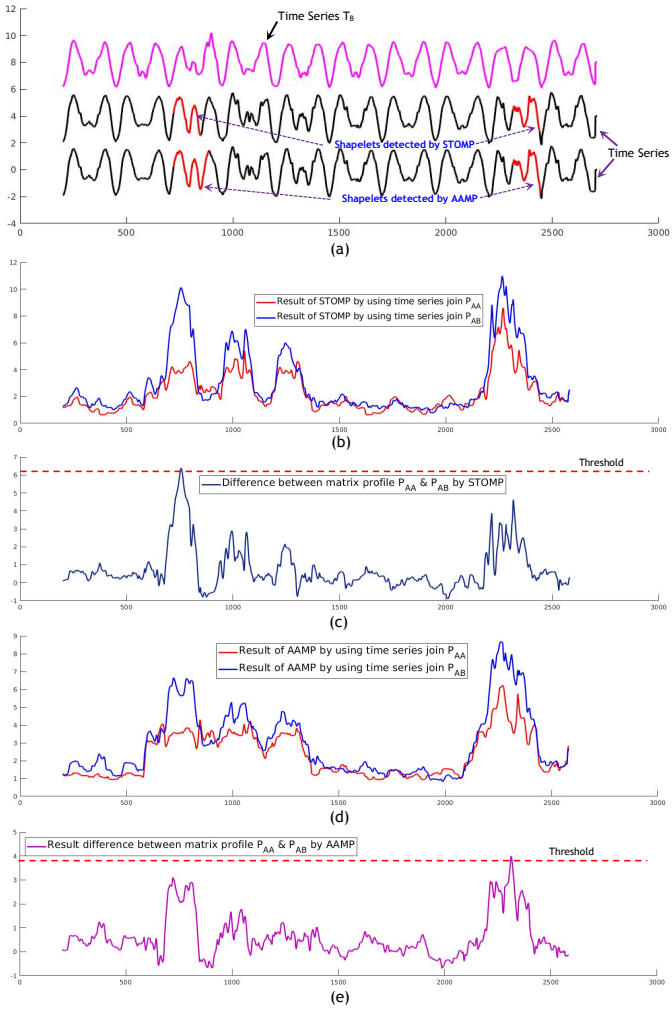


Figure 7: The time series shapelet discovery: (a) Two time series  $T_A$  and  $T_B$  formed by concatenating individual time series of class 1 and 0 respectively of the ArrowHead dataset. (b) (d) The matrix profile  $P_{AA}$  and  $P_{AB}$  by STOMP and AAMP algorithms respectively. (c) (e) The difference between  $P_{AB}$  and  $P_{AA}$ , by STOMP and AAMP algorithms respectively.

AAMP to compute  $P_{AA}$  and  $P_{AB}$  are 0.05 and 0.17 seconds respectively.

### SM: .3 Better performance of Z-Normalized distance over non-normalized distance

In the following Fig.8, 9, 10, 11, we have shown some interesting examples where the  $z$ -normalized distance has performed better than non normalized distance based matrix profile. The images in Fig.8, shows that  $z$ -normalized distance is able to find more possible locations of outliers by creating sharper peaks of matrix profile curve, compared to AAMP based matrix profile.

Whereas, from examples shown in Fig.9, we can visualize that  $z$ -normalized based matrix profiles (by STOMP algorithm) are able to show better and relevant possible outliers by detecting multiple and sharper peaks (marked by red circles), compared to AAMP based matrix profile. The detection of

multiple possible outliers location by  $z$ -normalized based matrix profile would help the data analyst and domain experts to manually validate it's legitimacy as they will have more options of possible outliers.

In Fig.10, 11 also, we show several matrix profile plots where  $z$ -normalized based matrix profile is able to find different and extra location of possible outliers (compared to non-normalized based matrix profile). Some time these detected outliers by  $z$ -normalized based matrix profile are relevant and some times they are irrelevant. But, it will always give a handful of extra and different possible outliers locations for the domain experts.

### SM: .4 Independent join using AAMP algorithm

Previously, we have mentioned the self join case i.e.  $P_{AA}$  for any particular time series  $T_A$ . In this section, we explain the technique to perform independent join i.e.  $P_{AB}$  between two time series  $T_A$  and  $T_B$ . The objective is to perform the similarity search between *Query* (e.g.  $T_A$ ) and *Target* time series e.g.  $T_B$ ). The pseudo code of independent join is mentioned in Algorithm 4. The operation of this algorithm is visually illustrated in Fig. 13 by considering number of subsequence in  $T_A$  i.e.  $Idxs_Q = 8$  and number of subsequence in  $T_B$  i.e.  $Idxs_T = 21$ . The query and target subsequences are denoted by  $QSSq$  and  $TSSq$  respectively. The description of the algorithm is as follows: the line 1-5 is self-explanatory and has been described before. In line 6, we initialize two rows of both the arrays ( $tempP$ ) and  $tempI$  by  $\infty$  and 1 respectively. In line 7, we iteratively perform diagonal jump of  $Idxs_T - 1 \equiv n - m$  number of times (because there are total  $n - m + 1$  subsequences exists, hence we can't jump more than  $n - m$  number of times) and for each jump, we calculate the distance between subsequent query and target subsequences.

For example, when  $k = 0$  (i.e. diagonal jump equals to zero), the distance is computed between  $QSSq1$  v/s  $TSSq1$  followed by distance computation between  $QSSq2$  v/s  $TSSq2$  etc. (follow the yellow color cells and "1" symbol in Fig. 13). Then for  $k = 1$ , the distance is computed between  $QSSq1$  v/s  $TSSq2$  followed by distance computation between  $QSSq2$  v/s  $TSSq3$  etc. (follow the green color cells and "2" symbol in Fig. 13) and so on. In this way,  $k$  iterate for  $Idxs_T - 1$  number of times i.e we perform  $Idxs_T - 1$  numbers of diagonal jumps. But among all these jumps, until  $Idxs_T - Idxs_Q$  numbers of diagonal jumps, we can compute the distance between all the subsequent query subsequences and corresponding target subsequences (follow maroon color cells and "14" symbol in Fig. 13 where distances are calculated between  $QSSq1$  v/s  $TSSq14$ ,  $QSSq2$  v/s  $TSSq15$  etc.). If we take any more jumps after that then we can't compute the distance between all the query subsequences and corresponding target subsequences. This rationale is implemented in line 8-11 of Algorithm 13. If  $k \leq (Idxs_T - Idxs_Q)$  then  $\mathfrak{E}$  is equal to  $Idxs_Q$  which means that we can compute distance for all the query subsequences otherwise  $\mathfrak{E}$  is taken as  $Idxs_T - k$ ; that means we can calculate distance of  $\mathfrak{E}$  number of query subsequences, where in each iteration,  $\mathfrak{E}$  is obtained by subtracting/removing the already

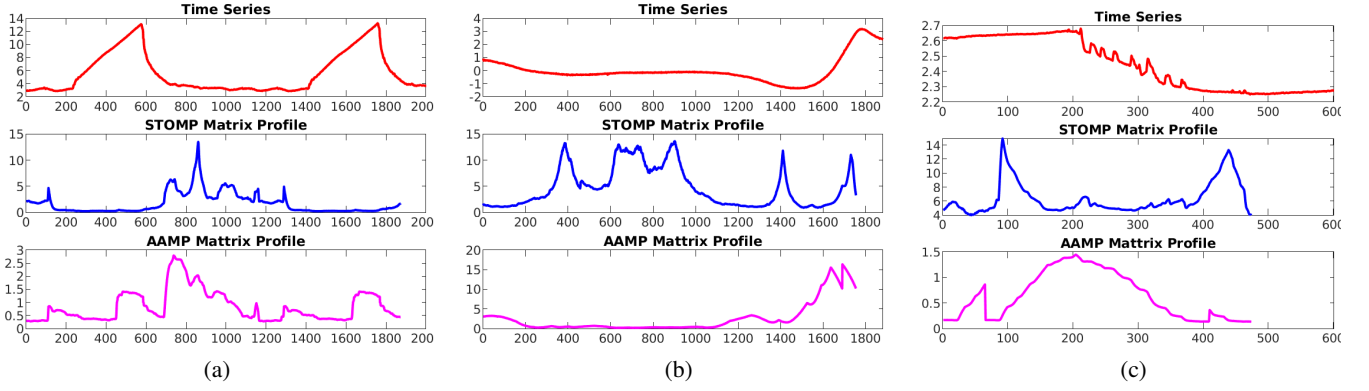


Figure 8: (a, b, c) **Top:** Time series from **PigAirwayPressure**, **InlineSkate**, **InsectEPGSmallTrain** dataset respectively. **Middle:** the matrix profile, obtained by STOMP algorithm; **Bottom:** The matrix profile, obtained by AAMP algorithm.

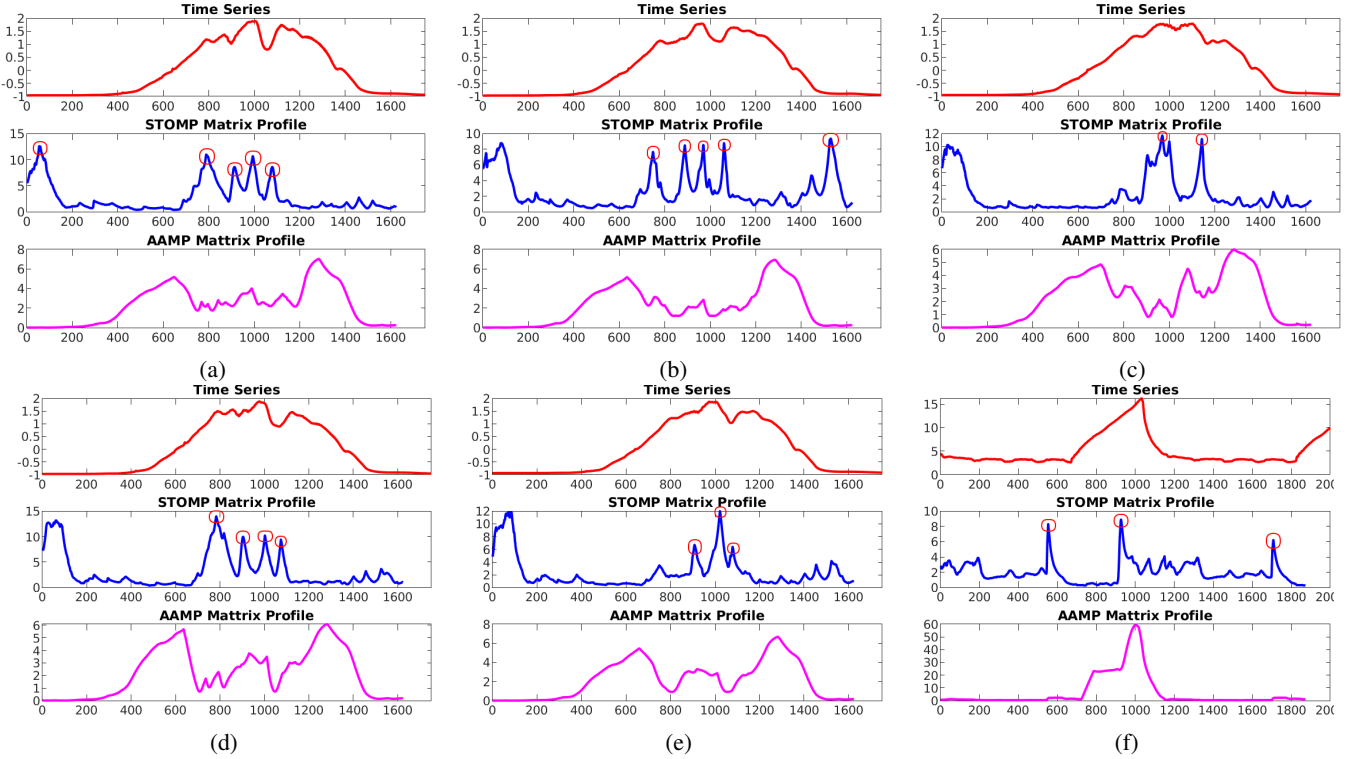


Figure 9: (a, b, c, d, e) **Top:** Various time series from **EthanolLevel** dataset. **Middle:** the matrix profile, obtained by STOMP algorithm; **Bottom:** The matrix profile, obtained by AAMP algorithm. (f) Time series from **PigAirwayPressure** dataset and corresponding matrix profile by STOMP and AAMP. These matrix profile plots shows that in several cases, the z-normalized based (STOMP) algorithm is able to find more clear (sharper peaks, marked by red circles) detection of outliers than AAMP.

taken jumps (i.e.  $k$ ) from total number of target subsequences ( $Idx_{ST}$ ) (follow the bottom yellow colored triangular regions in Fig. 13).

Now the distance between the  $1^{st}$  query subsequence and  $k + 1^{th}$  subsequence of target time series is calculated in line 16 and are saved at  $pI^{th}$  row of  $tempP$ . The value of  $pI$  is taken as 1 for the very first jump only ( $k = 0$ ) but for other jumps,  $pI$  is taken as 2. For  $k > 0$ , the distance between other subsequences are iteratively and incrementally calculated in Line 19-20. In each iteration of Line 19, we incrementally calculate the distance between  $i^{th}$  subsequence of  $Q$  and  $J^{th}$

subsequence of  $T$ . In line 20, the incremental distance is calculated by subtracting the term " $[t_{J-1} - q_{i-1}]$ ", (which represents  $1^{st}$  elements of two previous subsequences i.e.  $J-1^{th}$  and  $i-1^{th}$  subsequences of  $T$  and  $Q$  respectively) from previously computed distance i.e.  $dist$ , followed by adding the term " $[t_{J+m-1} - q_{i+m-1}]$ " (which represents the last elements of current subsequences i.e.  $J^{th}$  and  $i^{th}$  subsequences of  $T$  and  $Q$  respectively). Then the calculated distance values and respective indexes are iteratively updated in Line 22. Except the  $1^{st}$  jump (i.e.  $k = 0$ ), for every other jumps (when  $k > 0$ ), we first keep the distances at the  $2^{nd}$  row (i.e.

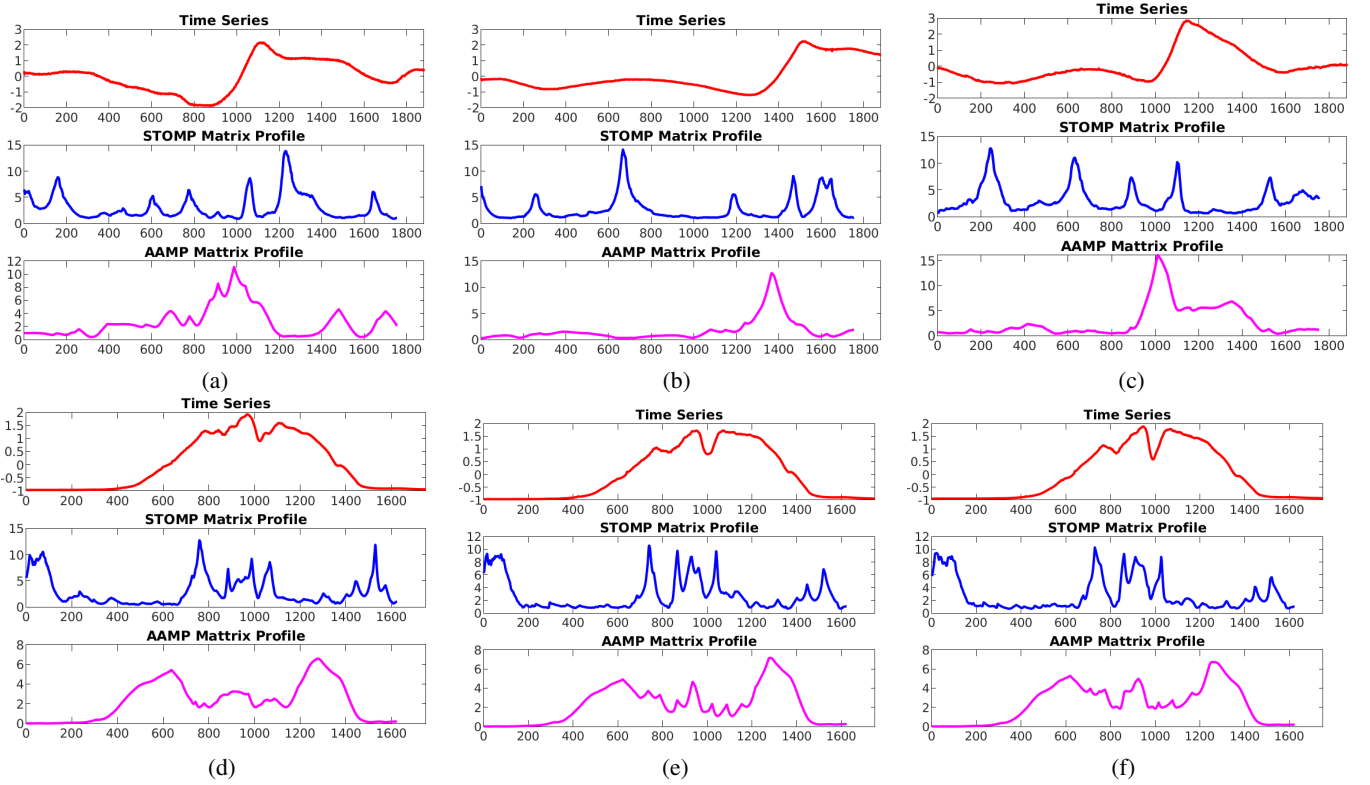


Figure 10: (a, b, c) **Top:** Various time series from **InlineSkate** dataset. **Middle:** the matrix profile, obtained by STOMP algorithm; **Bottom:** The matrix profile, obtained by AAMP algorithm. (f) Time series from **EthanolLevel** dataset and corresponding matrix profile by STOMP and AAMP.

$pI = 2$ ) then compare the previously stored best distances in  $1^{st}$  row of  $tempP$  array. These operation is performed in “Update\_Array()” function in Line 22.

After calculating all the distances in left to right direction (i.e. except the top cells, covered with red colored triangular region in Fig. 13), the distance calculations are performed from right to left direction. These operations are visually represented as red colored region at the top of Fig. 13. The operations for these cells or the distance computation between these subsequences of  $Q$  and  $T$  were not performed before. In line 23, we perform  $Idx_Q - 1$  number of jumps iteratively (notice that  $iJump$  starts here from 1 instead of 0 because we want to perform distance computations of  $QSSq8$  v/s  $TSSq7$ ,  $QSSq7$  v/s  $TSSq6$  etc. instead of  $QSSq8$  v/s  $TSSq8$ ,  $QSSq7$  v/s  $TSSq7$  etc. which were already computed before). For every jump in Line 23, we initiate the distance computation between the last query i.e.  $Idx_Q^{th}$  query subsequence and  $tSt^{th}$  subsequence of  $T$ . The value of  $tSt$  is computed by  $k$  number of jumps from  $Idx_Q$  number of subsequences (see Line 24).

In line 28-31, the distance between  $tSt^{th}$  subsequence from  $T$  and  $qSt^{th}$  subsequence from  $Q$  are iteratively calculated in an incremental fashion. To calculate the distance incrementally, in line 31, we subtract the term “ $[t_{tSt} - q_{qSt}]$ ”, which represents  $1^{st}$  elements of two previous subsequences i.e.  $tSt^{th}$  and  $qSt^{th}$  elements of  $T$  and  $Q$  respectively from previously computed distance i.e.  $dist$  and adding the term

“ $[t_{tSt+m} - q_{tSt+m}]$ ”, which represents the last elements of current subsequences i.e.  $tSt + m^{th}$  and  $qSt + m^{th}$  elements of  $T$  and  $Q$  respectively. Then the calculated distance values and respective indexes are iteratively updated in Line 32-33.

The visual representation of the query subsequences which are considered in each iteration are shown as top red colored region in Fig. 13, where it can be seen that in  $1^{st}$  iteration, we operate on  $QSSq8$ - $QSSq2$  (follow the blue colored cells) and in  $2^{nd}$  iteration, we operate on  $QSSq8$ - $QSSq3$  and so on.

The independent join i.e.  $J_{AB}$  computation by ACAMP algorithm can be done by following the same strategy/approach of calculating the distances between subsequences of query and target time series as it is done in the case of AAMP algorithm. The only difference is that here we need to calculate  $z$ -normalized euclidean distance (see violet colored lines in Algorithm 2) instead of classical euclidean distance. We try to keep the same line numbering as in Algorithm 4 to keep the conformity in line numbering. The extra lines, related to  $z$ -normalized euclidean distance computations are numerated in Roman numerals (i.e.  $i, ii, iii, \dots$ ) to distinguish them from the common lines between Algorithm 2 and Algorithm 4.

To calculate the  $Z$ -normalized euclidean distance between two subsequent subsequences, we first compute the mean ( $\mu_Q, \mu_T$ ) and standard deviation ( $\sigma_Q, \sigma_T$ ) of all the possible subsequences of  $T$  and  $Q$  in line  $i - ii$ . The distance (in Line 16) between the  $1^{st}$  ( $q$ ) and  $k + 1^{th}$  ( $t$ ) subsequence is calculated by using the means (i.e.  $\mu_Q$  and  $\mu_T$ ) and standard

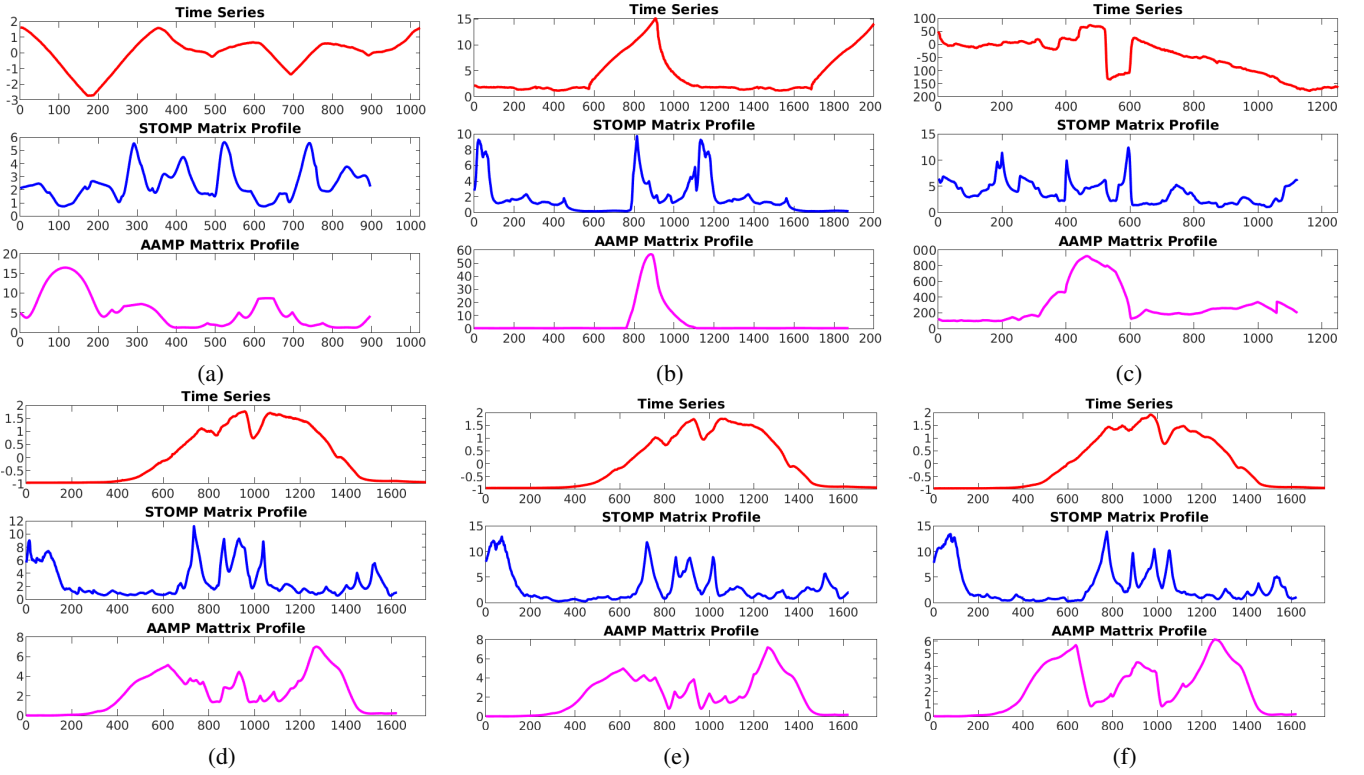


Figure 11: (a, b, c) **Top:** Time series from **MixedShapesRegularTrain**, **PigAirwayPressure**, **EOGVerticalSignal** dataset. The discord is visible in it. **Middle:** the matrix profile, obtained by STOMP algorithm; **Bottom:** The matrix profile, obtained by AAMP algorithm. (d, e, f) Time series from **EthanolLevel** dataset and corresponding matrix profile by STOMP and AAMP algorithm respectively.

deviations (i.e.  $\sigma_Q$  and  $\sigma_T$ ) of  $q$  and  $t$  respectively. The incremental  $Z$ -normalized distance in Line 20 is calculated by using means ( $\mu_q, \mu_t$ ) and standard deviations ( $\sigma_q, \sigma_t$ ) to calculate  $prod$  in an incremental manner. The variable  $prod$  is computed by subtracting  $Q[i-1] \times T[J-1]$  term and by adding  $Q[i+m-1] \times T[J+m-1]$  term with previously calculated  $prod$  value. In this formulation, the  $Q[i-1]$  and  $T[J-1]$  terms represents the first elements of previous (i.e.  $i-1^{th}$  and  $J-1^{th}$ ) subsequences (where the current subsequence is represented by  $i^{th}$  and  $J^{th}$  indexes). Whereas, the  $Q[i+m-1]$  and  $T[J+m-1]$  terms represent the last elements of current i.e.  $i^{th}$  and  $J^{th}$  subsequences. Then the distance is calculated by using Equation ?? . In the same manner, we compute the  $Z$ -normalized euclidean distance of  $qSt^{th}$  and  $tSt^{th}$  subsequences of  $Q$  and  $T$  respectively in Line  $ix - 27$ , whereas the incremental euclidean distance between  $tSt^{th}$  and  $qSt^{th}$  subsequences is calculated in Line  $xii - 32$  in the same manner as it was done in Line  $vi - 20$ .

### SM: .5 Fast Calculation of Mean and Standard Deviation :

The fast calculation of mean ( $\mu$ ) and standard deviation ( $\sigma$ ) of a vector of elements ( $x$ ) is proposed by Rakthanmanon et.al [15]. The technique needs only one scan through the sample to compute the mean and standard deviation of all the subsequences. The mean of the subsequences can be calculated

by keeping two running sums of the long time series which have a lag of exactly  $m$  values.

$$\mu = \frac{1}{m} \left( \sum_{i=1}^k x_i - \sum_{i=1}^{k-m} x_i \right) \quad \sigma^2 = \frac{1}{m} \left( \sum_{i=1}^k x_i^2 - \sum_{i=1}^{k-m} x_i^2 \right) - \mu^2 \quad (22)$$

In the same manner, the sum of squares of the subsequences can also be calculated which are used to compute the standard deviation of all the subsequences by using the Equations 22.



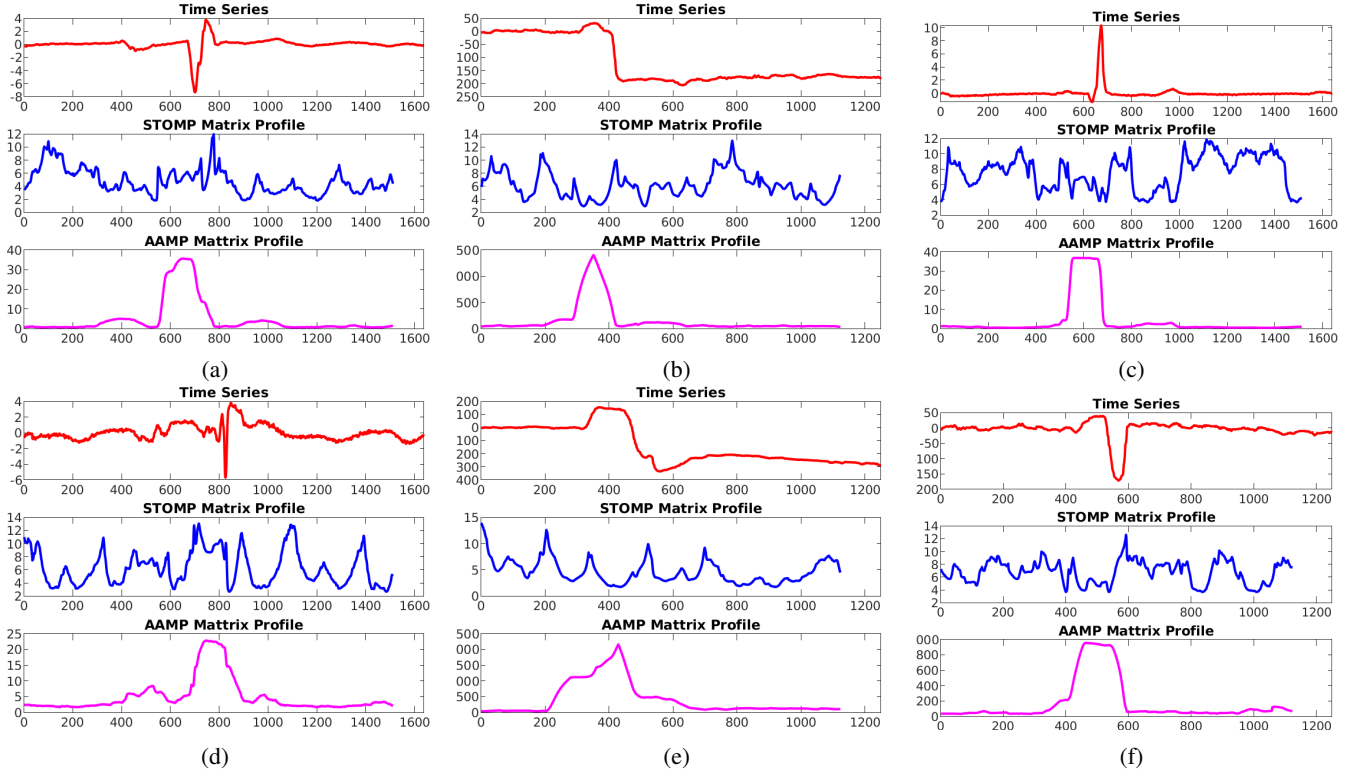


Figure 12: (a) **Top:** The randomly chosen time series from **CinCECGTorso** dataset. The discord is visible in it. **Middle:** the matrix profile, obtained by STOMP algorithm; **Bottom:** The matrix profile, obtained by AAMP algorithm. (b) The randomly chosen time series from **EOGVerticalSignal** dataset and corresponding matrix profile by STOMP and AAMP algorithms. (c) Another randomly chosen time series from **CinCECGTorso** dataset (d) Another randomly chosen time series from **CinCECGTorso** dataset (e) The randomly chosen time series from **EOGHorizontalSignal** dataset (f) Another randomly chosen time series from **EOGVerticalSignal** dataset

	Q11q1	Q11q2	Q11q3	Q11q4	Q11q5	Q11q6	Q11q7	Q11q8
T11q1	1	22	23	24	25	26	27	28
T11q2	2	1	22	23	24	25	26	27
T11q3	3	2	1	22	23	24	25	26
T11q4	4	3	2	1	22	23	24	25
T11q5	5	4	3	2	1	22	23	24
T11q6	6	5	4	3	2	1	22	23
T11q7	7	6	5	4	3	2	1	22
T11q8	8	7	6	5	4	3	2	1
T11q9	9	8	7	6	5	4	3	2
T11q10	10	9	8	7	6	5	4	3
T11q11	11	10	9	8	7	6	5	4
T11q12	12	11	10	9	8	7	6	5
T11q13	13	12	11	10	9	8	7	6
T11q14	14	13	12	11	10	9	8	7
T11q15	15	14	13	12	11	10	9	8
T11q16	16	15	14	13	12	11	10	9
T11q17	17	16	15	14	13	12	11	10
T11q18	18	17	16	15	14	13	12	11
T11q19	19	18	17	16	15	14	13	12
T11q20	20	19	18	17	16	15	14	13
T11q21	21	20	19	18	17	16	15	14

TSSq = Target Sub-sequence; QSSq = Query Sub-sequence

Figure 13: a) The subsequences of query and target time series are arranged in a matrix to better understand the functioning of AAMP algorithm. By looking at the cells of the matrix, we can see in which iteration, the distance of two subsequences is calculated. Different iterations are represented by different colors.

---

**Algorithm 4:** Independent AAMP
 

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**Input:**  $T$ : target time series;  $Q$ : query time series;  $n$ : length of time series  $T$ ;  $\Omega$ : length of time series  $Q$ ;  $m$ : subsequence length

**Output:**  $P$ : Matrix profile;  $I$ : Matrix profile Indexes;  
**begin**

```

   $Idx_T = n - m + 1$    $Idx_Q = \Omega - m + 1$ 
   $Flag = False$ 
  for  $i = 1$  to  $Idx_Q$  do
     $P[i] = \infty$    $I[i] = 1$    $\triangleright$  initialize two arrays
     $tempP[1:2, i] = \infty$    $tempI[1:2, i] = 1$ 
  for  $k = 0$  to  $Idx_T - 1$  do
    if  $k \leq Idx_T - Idx_Q$  then
       $\mathfrak{E} \leftarrow Idxs_Q$ 
    else
       $\mathfrak{E} \leftarrow Idxs_T - k$ 
    if  $k == 0$  then
       $pI \leftarrow 1$ 
    else
       $pI \leftarrow 2$ ;   $Flag = True$ 
     $dist = Euc\_Distance(Q_{1:m}, T_{k+1:m+k})$ 
     $tempP[pI, 1] \leftarrow dist$ ;   $tempI[pI, 1] \leftarrow k + 1$ 
    for  $i = 2$  to  $\mathfrak{E}$  do
       $J = k + i$ 
       $dist = \sqrt{(dist^2 - (t_{J-1} - q_{i-1})^2 + (t_{J+m-1} - q_{i+m-1})^2)}$ 
       $tempP[pI, i] = dist$ ;   $tempI[pI, i] = J$ 
      if  $Flag == True$  then
         $[tempP, tempI] \leftarrow Update\_Array(1, \mathfrak{E}, tempP, tempI)$ 
  for  $k = 1$  to  $(Idx_Q - 1)$  do
     $\mathfrak{E} = Idxs_Q - k$ ;   $tSt = Idxs_Q - k$ 
     $qSt = Idxs_Q$ 
     $dist = Euc\_Distance(Q_{qSt : qSt+m-1}, T_{tSt : tSt+m-1})$ 
     $tempP[qSt] = dist$ ;   $tempI[qSt] = tSt$ 
    for  $i = 2$  to  $\mathfrak{E}$  do
       $tSt = Idxs_Q - (i - 1) - k$ 
       $qSt = Idxs_Q - (i - 1)$ 
       $dist = \sqrt{(dist^2 - (t_{iSt} - q_{qSt})^2 + (t_{iSt+m} - q_{qSt+m})^2)}$ 
       $tempP[pI, qSt] = dist$ ;   $tempI[pI, qSt] = tSt$ 
       $[tempP, tempI] \leftarrow Update\_Array(qSt, Idx_Q, tempP, tempI)$ 
  for  $i = 1$  to  $Idx_Q$  do
     $tempP[i] = \sqrt{tempP[i]}$ 
   $P[1, :] = tempP[1, :]$ ;   $I[1, :] = tempI[1, :]$ 

```

---



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**Function**  $Update\_Array(st, ed, tempP, tempI)$ :

```

  for  $p = st$  to  $ed$  do
    if  $tempP[1, p] > tempP[pI, p]$  then
       $S = p + st - 1$ 
       $tempP[1, S] = tempP[pI, S]$ 
       $tempI[1, S] = tempI[pI, S]$ 
  return  $tempP, tempI$ 

```

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**Algorithm 5:** Independent ACAMP
 

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**Input:**  $T$ : target time series;  $Q$ : query time series;  $n$ : length of time series  $T$ ;  $\mathfrak{Q}$ : length of time series  $Q$ ;  $m$ : subsequence length

**Output:**  $P$ : Matrix profile;  $I$ : Matrix profile Indexes;  
**begin**

```

i.    $[\mu_T, \sigma_T] \leftarrow \text{ComputeMeanStd}(T)$ 
       $\triangleright$  For details, see section SM: .5
ii.   $[\mu_Q, \sigma_Q] \leftarrow \text{ComputeMeanStd}(Q)$ 
7   for  $k = 0$  to  $\text{Idx}_T - 1$  do
      ..
iii.   $\mathbf{q} \leftarrow Q_{1:m}$  ;  $\mathbf{t} \leftarrow T_{k+1:m+k}$ 
iv.    $\mu_q \leftarrow \mu_Q[1]$  ;  $\mu_t \leftarrow \mu_T[1]$ 
v.     $\sigma_q \leftarrow \sigma_Q[1]$  ;  $\sigma_t \leftarrow \sigma_T[1]$ 
16    $[dist, prod] =$ 
       $Z\_Norm\_Euc\_Dis(\mathbf{q}, \mathbf{t}, m, \mu_q, \mu_t, \sigma_q, \sigma_t)$ 
17    $tempP[pI, 1] \leftarrow dist$ ;  $tempI[pI, 1] \leftarrow k + 1$ 
18   for  $i = 2$  to  $\mathfrak{E}$  do
19      $J = k + i$ 
vi.     $\mu_q \leftarrow \mu_Q[i]$  ;  $\mu_t \leftarrow \mu_T[J]$ 
vii.    $\sigma_q \leftarrow \sigma_Q[i]$  ;  $\sigma_t \leftarrow \sigma_T[J]$ 
viii.   $prod =$ 
       $prod - (Q[i-1] \times T[J-1]) + (Q[i+m-1] \times T[J+m-1])$ 
20      $dist = 2 \times \left( m - \frac{prod - (m \times \mu_q \times \mu_t)}{\sigma_q \times \sigma_t} \right)$ 
21      $tempP[pI, i] = dist$ ;  $tempI[pI, i] = J$ 
22   if  $Flag == True$  then
      ..
24   for  $k = 1$  to  $(\text{Idx}_Q - 1)$  do
25      $\mathfrak{E} = \text{Idx}_Q - k$ ;  $tSt = \text{Idx}_Q - k$ 
26      $qSt = \text{Idx}_Q$ 
ix.     $\mathbf{q} \leftarrow Q_{qSt:qSt+m-1}$  ;  $\mathbf{t} \leftarrow T_{tSt:tSt+m-1}$ 
x.      $\mu_q \leftarrow \mu_Q[qSt]$  ;  $\mu_t \leftarrow \mu_T[tSt]$ 
xi.     $\sigma_q \leftarrow \sigma_Q[qSt]$  ;  $\sigma_t \leftarrow \sigma_T[tSt]$ 
27      $[dist, prod] =$ 
       $Z\_Norm\_Euc\_Dis(\mathbf{q}, \mathbf{t}, m, \mu_q, \mu_t, \sigma_q, \sigma_t)$ 
28      $tempP[qSt] = dist$ ;  $tempI[qSt] = tSt$ ;
29     for  $i = 2$  to  $\mathfrak{E}$  do
30        $tSt = \text{Idx}_Q - (i - 1) - k$ 
31        $qSt = \text{Idx}_Q - (i - 1)$ 
xii.    $\mu_q \leftarrow \mu_Q[qSt]$  ;  $\mu_t \leftarrow \mu_T[tSt]$ 
xiii.   $\sigma_q \leftarrow \sigma_Q[qSt]$  ;  $\sigma_t \leftarrow \sigma_T[tSt]$ 
xiv.    $prod =$ 
       $prod - (Q[qSt] \times T[tSt]) + (Q[qSt+m] \times T[tSt+m])$ 
32      $dist = 2 \times \left( m - \frac{prod - (m \times \mu_q \times \mu_t)}{\sigma_q \times \sigma_t} \right)$ 
33      $tempP[pI, qSt] = dist$ ;  $tempI[pI, qSt] =$ 
       $tSt$ 
34      $[tempP, tempI] \leftarrow \text{Update\_Array}(qSt,$ 
       $\text{Idx}_Q, tempP, tempI)$ 
37    $P[1, :] = tempP[1, :]$ ;  $I[1, :] = tempI[1, :]$ 

```

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